- Independent Registers and Enables for A and B Buses
- Multiplexed Real-Time and Stored Data
- Inverting Data Paths
- Flow-Through Architecture Optimizes PCB Layout
- Center-Pin $V_{C C}$ and GND Configurations Minimize High-Speed Switching Noise
- EPIC ${ }^{\text {TM }}$ (Enhanced-Performance Implanted CMOS) 1- $\mu \mathrm{m}$ Process
- 500-mA Typical Latch-Up Immunity at $125^{\circ} \mathrm{C}$
- Package Options Include Plastic Small-Outline Packages and Standard Plastic 300-mil DIPs

DW OR NT PACKAGE
(TOP VIEW)


## description

These devices consist of bus transceiver circuits, D-type flip-flops, and control circuitry arranged for multiplexed transmission of data directly from the data bus or from the internal storage registers. Output-enable (OEAB and $\overline{O E B A}$ ) inputs are provided to control the transceiver functions. The select-control (SAB and SBA) inputs are provided to select whether real-time or stored data is transferred. A low input level selects real-time data, and a high input level selects stored data. Figure 1 illustrates the four fundamental bus-management functions that can be performed with the 74AC11651.
Data on the A or B bus, or both, can be stored in the internal D flip-flops by low-to-high transitions at the appropriate clock (CLKAB or CLKBA) inputs regardless of the select- or enable-control pins. When SAB and SBA are in the real-time transfer mode, it is also possible to store data without using the internal D-type flip-flops by simultaneously enabling OEAB and $\overline{O E B A}$. In this configuration, each output reinforces its input. Thus, when all the other data sources to the two sets of bus lines are at high impedance, each set will remain at its last state.
The 74AC11651 is characterized for operation from $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$.


Figure 1. Bus-Management Functions

FUNCTION TABLE

| INPUTS |  |  |  |  |  | DATA I/O |  | OPERATION OR FUNCTION |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| OEAB | OEBA | CLKAB | CLKBA | SAB | SBA | A1 THRU A8 | B1 THRU B8 |  |
| L | H | H or L | H or L | X | X | Input | Input | Isolation |
| L | H | $\uparrow$ | $\uparrow$ | X | X | Input | Input | Store $A$ and $B$ data |
| X | H | $\uparrow$ | H or L | X | X | Input | Unspecified $\dagger$ | Store A, hold B |
| H | H | $\uparrow$ | $\uparrow$ | x $\ddagger$ | X | Input | Output | Store A in both registers |
| L | X | H or L | $\uparrow$ | X | X | Unspecified $\dagger$ | Input | Hold A, store B |
| L | L | $\uparrow$ | $\uparrow$ | X | X $\ddagger$ | Output | Input | Store B in both registers |
| L | L | X | X | X | L | Output | Input | Real-time $\bar{B}$ data to $A$ bus |
| L | L | X | H or L | X | H | Output | Output | Stored $\bar{B}$ data to $A$ bus |
| H | H | X | X | L | X | Input | Output | Real-time $\bar{A}$ data to $B$ bus |
| H | H | H or L | X | H | X | Input | Output | Stored $\bar{A}$ data to $B$ bus |
| H | L | H or L | H or L | H | H | Output | Output | Stored $\bar{A}$ data to $B$ bus and stored $B$ data to $A$ bus |

$\dagger$ The data output functions may be enabled or disabled by various signals at the OEAB or $\overline{O E B A}$ inputs. Data input functions are always enabled, i.e., data at the bus pins will be stored on every low-to-high transition on the clock inputs.
$\ddagger$ When select control is low, clocks can occur simultaneously so long as allowances are made for propagation delays from $A$ to $B(B$ to $A)$ plus setup and hold times. When select control is high, clocks must be staggered in order to load both registers.

## logic symbol§


§ This symbol is in accordance with ANSI/IEEE Std 91-1984 and IEC Publication 617-12.

## logic diagram (positive logic)


absolute maximum ratings over operating free-air temperature range (unless otherwise noted) $\dagger$

$\dagger$ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
NOTE 1: The input and output voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

## recommended operating conditions

|  |  |  | MIN | NOM | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply voltage |  | 3 | 5 | 5.5 | V |
| $\mathrm{V}_{\mathrm{IH}}$ | High-level input voltage | $\mathrm{V}_{\mathrm{CC}}=3 \mathrm{~V}$ | 2.1 |  |  | V |
|  |  | $\mathrm{V}_{\mathrm{CC}}=4.5 \mathrm{~V}$ | 3.15 |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}$ | 3.85 |  |  |  |
| $\mathrm{V}_{\mathrm{IL}}$ | Low-level input voltage | $\mathrm{V}_{\mathrm{CC}}=3 \mathrm{~V}$ |  |  | 0.9 | V |
|  |  | $\mathrm{V}_{C C}=4.5 \mathrm{~V}$ |  |  | 1.35 |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}$ |  |  | 1.65 |  |
| $\mathrm{V}_{1}$ | Input voltage |  | 0 |  | $\mathrm{V}_{\text {CC }}$ | V |
| $\mathrm{V}_{\mathrm{O}}$ | Output voltage |  | 0 |  | $\mathrm{V}_{\text {CC }}$ | V |
| ${ }^{\mathrm{IOH}}$ | High-level output current | $\mathrm{V}_{\text {CC }}=3 \mathrm{~V}$ |  |  | -4 | mA |
|  |  | $\mathrm{V}_{\mathrm{CC}}=4.5 \mathrm{~V}$ |  |  | -24 |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}$ |  |  | -24 |  |
| ${ }^{\text {IOL }}$ | Low-level output current | $\mathrm{V}_{\mathrm{CC}}=3 \mathrm{~V}$ |  |  | 12 | mA |
|  |  | $\mathrm{V}_{\mathrm{CC}}=4.5 \mathrm{~V}$ |  |  | 24 |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}$ |  |  | 24 |  |
| $\Delta t / \Delta v$ | Input transition rise or fall rate |  | 0 |  | 10 | ns/V |
| $\mathrm{T}_{\mathrm{A}}$ | Operating free-air temperature |  | -40 |  | 85 | ${ }^{\circ} \mathrm{C}$ |

electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)

| PARAMETER |  | TEST CONDITIONS |  | $\mathrm{V}_{\mathrm{Cc}}$ | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN |  | TYP | MAX |  |  |  |
| $\mathrm{V}_{\mathrm{OH}}$ |  |  | $\mathrm{IOH}=-50 \mu \mathrm{~A}$ |  | 3 V | 2.9 |  |  | 2.9 |  | V |
|  |  | 4.5 V |  |  | 4.4 |  |  | 4.4 |  |  |  |
|  |  | 5.5 V |  |  | 5.4 |  |  | 5.4 |  |  |  |
|  |  | $\mathrm{I} \mathrm{OH}=-4 \mathrm{~mA}$ |  | 3 V | 2.58 |  |  | 2.48 |  |  |  |
|  |  | $\mathrm{IOH}=-24 \mathrm{~mA}$ |  | 4.5 V | 3.94 |  |  | 3.8 |  |  |  |
|  |  | 5.5 V | 4.94 |  |  | 4.8 |  |  |  |  |  |
|  |  | $\mathrm{IOH}=-75 \mathrm{~mA} \dagger$ |  | 5.5 V |  |  |  | 3.85 |  |  |  |
| $\mathrm{V}_{\mathrm{OL}}$ |  |  |  | $\mathrm{l} \mathrm{OL}=50 \mu \mathrm{~A}$ |  | 3 V |  |  | 0.1 |  | 0.1 | V |
|  |  | 4.5 V |  |  |  |  | 0.1 |  | 0.1 |  |  |  |
|  |  | 5.5 V |  |  |  |  | 0.1 |  | 0.1 |  |  |  |
|  |  | $\mathrm{IOL}=12 \mathrm{~mA}$ |  | 3 V |  |  | 0.36 |  | 0.44 |  |  |  |
|  |  | $\mathrm{lOL}=24 \mathrm{~mA}$ |  | 4.5 V |  |  | 0.36 |  | 0.44 |  |  |  |
|  |  | 5.5 V |  |  | 0.36 |  | 0.44 |  |  |  |  |  |
|  |  | $\mathrm{IOL}=75 \mathrm{~mA} \dagger$ |  | 5.5 V |  |  |  |  | 1.65 |  |  |  |
| 1 | Control inputs |  |  | $\mathrm{V}_{1}=\mathrm{V}_{\mathrm{CC}}$ or GND |  | 5.5 V |  |  | $\pm 0.1$ |  | $\pm 1$ | $\mu \mathrm{A}$ |
| loz ${ }^{\ddagger}$ | A or B ports | $\mathrm{V}_{\mathrm{O}}=\mathrm{V}_{\mathrm{CC}}$ or GND |  | 5.5 V |  |  | $\pm 0.5$ |  | $\pm 5$ | $\mu \mathrm{A}$ |  |  |
| ICC |  | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {CC }}$ or GND, | $\mathrm{I}=0$ | 5.5 V |  |  | 8 |  | 80 | $\mu \mathrm{A}$ |  |  |
| $\mathrm{C}_{\mathrm{i}}$ | Control inputs | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{CC}}$ or GND |  | 5 V |  | 4.5 |  |  |  | pF |  |  |
| $\mathrm{Cio}_{1}$ | A or B ports | $\mathrm{V}_{\mathrm{O}}=\mathrm{V}_{\text {CC }}$ or GND |  | 5 V |  | 10 |  |  |  | pF |  |  |

$\dagger$ Not more than one output should be tested at a time, and the duration of the test should not exceed 10 ms .
$\ddagger$ For I/O ports, the parameter loZ includes the input leakage current.

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timing requirements over recommended operating free-air temperature range, $\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}$ (unless otherwise noted) (see Figure 2)

|  |  | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | MAX |  |  |  |
| $\mathrm{f}_{\text {clock }}$ | Clock frequency | 0 | 45 | 0 | 45 | MHz |
| $\mathrm{t}_{\mathrm{w}}$ | Pulse duration, CLK high or low | 10 |  | 10 |  | ns |
| $\mathrm{t}_{\text {su }}$ | Setup time, A or B before CLKAB $\uparrow$ or CLKBA $\uparrow$ | 6.5 |  | 6.5 |  | ns |
| th | Hold time, A or B after CLKAB $\uparrow$ or CLKBA $\uparrow$ | 0 |  | 0 |  | ns |

timing requirements over recommended operating free-air temperature range, $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ (unless otherwise noted) (see Figure 2)

|  |  | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | MIN | MAX |  |  |  |
| $\mathrm{f}_{\text {clock }}$ | Clock frequency | 0 | 90 | 0 | 90 | MHz |
| $\mathrm{t}_{\mathrm{w}}$ | Pulse duration, CLK high or low | 5.5 |  | 5.5 |  | ns |
| $\mathrm{t}_{\text {su }}$ | Setup time, A or B before CLKAB $\uparrow$ or CLKBA $\uparrow$ | 4.5 |  | 4.5 |  | ns |
| th | Hold time, A or B after CLKAB $\uparrow$ or CLKBA $\uparrow$ | 0.5 |  | 0.5 |  | ns |

switching characteristics over recommended operating free-air temperature range, $\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}$ (unless otherwise noted) (see Figure 2)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN | TYP | MAX |  |  |  |
| $f_{\text {max }}$ |  |  | 45 |  |  | 45 |  | MHz |
| tPLH | A or B | B or A | 3.2 | 7.7 | 12.1 | 3.2 | 14 | ns |
| tPHL |  |  | 4.3 | 9.5 | 14.6 | 4.3 | 16.1 |  |
| tPLH | CLKBA or CLKAB | A or B | 4.6 | 9.8 | 15 | 4.6 | 17.2 | ns |
| tPHL |  |  | 5.4 | 11.5 | 17.5 | 5.4 | 19.2 |  |
| tPLH | SBA or SABT (A or B high) | A or B | 3.8 | 8.6 | 13.3 | 3.8 | 15.3 | ns |
| tPHL |  |  | 4.8 | 10.2 | 15.5 | 4.8 | 17.1 |  |
| tPLH | SBA or SAB $\dagger$ <br> (A or B low) | A or B | 3.4 | 8.1 | 12.7 | 3.4 | 14.6 | ns |
| tPHL |  |  | 5 | 10.3 | 15.5 | 5 | 17.1 |  |
| tPZH | OEBA | A | 4.6 | 9.8 | 14.9 | 4.6 | 16.9 | ns |
| tpZL |  |  | 5.3 | 12.1 | 18.9 | 5.3 | 21.3 |  |
| tPHZ | OEBA | A | 4.4 | 6.6 | 8.8 | 4.4 | 9.2 | ns |
| tplZ |  |  | 3.8 | 5.8 | 7.8 | 3.8 | 8.1 |  |
| tPZH | OEAB | B | 4.9 | 10.2 | 15.5 | 4.9 | 17.6 | ns |
| tPZL |  |  | 5.5 | 12.2 | 18.8 | 5.5 | 21.2 |  |
| tPHZ | OEAB | B | 4.4 | 6.7 | 8.9 | 4.4 | 9.3 | ns |
| tPLZ |  |  | 3.5 | 5.7 | 7.8 | 3.5 | 8 |  |

$\dagger$ These parameters are measured with the internal output state of the storage register opposite to that of the bus input.
switching characteristics over recommended operating free-air temperature range, $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ (unless otherwise noted) (see Figure 2)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  |  | MIN | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | MIN | TYP | MAX |  |  |  |
| $f_{\text {max }}$ |  |  | 90 |  |  | 90 |  | MHz |
| tPLH | A or B | B or A | 2.6 | 5.3 | 8 | 2.6 | 9.1 | ns |
| tpHL |  |  | 3.5 | 6.5 | 9.4 | 3.5 | 10.5 |  |
| tPLH | CLKBA or CLKAB | A or B | 3.8 | 6.8 | 10 | 3.8 | 11.4 | ns |
| tpHL |  |  | 4.7 | 8.1 | 11.5 | 4.7 | 12.8 |  |
| tPLH | SBA or SAB ${ }^{\top}$ <br> (A or B high) | A or B | 3.2 | 6 | 8.8 | 3.2 | 10.1 | ns |
| tPHL |  |  | 3.9 | 7 | 10.1 | 3.9 | 11.2 |  |
| tPLH | SBA or SABT <br> (A or B low) | A or B | 2.9 | 5.7 | 8.5 | 2.9 | 9.5 | ns |
| tPHL |  |  | 4.1 | 7.2 | 10.3 | 4.1 | 11.4 |  |
| tPZH | OEBA | A | 3.9 | 6.9 | 9.8 | 3.9 | 11.1 | ns |
| tPZL |  |  | 4.2 | 7.6 | 11 | 4.2 | 12.5 |  |
| tPHZ | OEBA | A | 4.1 | 5.9 | 7.6 | 4.1 | 8 | ns |
| tPLZ |  |  | 3.5 | 5.2 | 6.8 | 3.5 | 7.1 |  |
| tPZH | OEAB | B | 4.2 | 5.9 | 10.4 | 4.2 | 11.8 | ns |
| tPZL |  |  | 4.5 | 8 | 11.4 | 4.5 | 12.9 |  |
| tpHZ | OEAB | B | 4.2 | 6 | 7.8 | 4.2 | 8.2 | ns |
| tplZ |  |  | 3.3 | 5.1 | 6.9 | 3.3 | 7.2 |  |

operating characteristics, $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$

| PARAMETER |  |  | TEST CONDITIONS |  | TYP | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{C}_{\text {pd }}$ | Power dissipation capacitance per transceiver | Outputs enabled | $C_{L}=50 \mathrm{pF}$, | $\mathrm{f}=1 \mathrm{MHz}$ | 64 | pF |
|  |  | Outputs disabled |  |  | 14 |  |

## PARAMETER MEASUREMENT INFORMATION



| TEST | S1 |
| :---: | :---: |
| tPLH/tPHL | Open |
| tPLZ/tPZL | $2 \times \mathrm{V}$ CC |
| $\mathrm{tPHZ}^{\text {/ }}$ PZ ${ }^{\text {l }}$ | GND |



VOLTAGE WAVEFORMS
PROPAGATION DELAY TIMES


Voltage waveforms
ENABLE AND DISABLE TIMES

NOTES: A. $C_{L}$ includes probe and jig capacitance.
B. All input pulses are supplied by generators having the following characteristics: $\mathrm{PRR} \leq 10 \mathrm{MHz}, \mathrm{Z}_{\mathrm{O}}=50 \Omega, \mathrm{t}_{\mathrm{r}} \leq 3 \mathrm{~ns}, \mathrm{t}_{\mathrm{f}} \leq 3 \mathrm{~ns}$. For testing pulse duration: $\mathrm{t}_{\mathrm{r}}=\mathrm{t}_{\mathrm{f}}=1$ to 3 ns . Pulse polarity can be either high-to-low-to-high or low-to-high-to-low.
C. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
D. The outputs are measured one at a time with one transition per measurement.

Figure 2. Load Circuit and Voltage Waveforms

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