![intersil logo]

HI5662

Dual 8-Bit, 60MSPS A/D Converter with Internal Voltage Reference

The HI5662 is a monolithic, dual 8-Bit, 60MSPS analog-to-digital converter fabricated in an advanced CMOS process. It is designed for high speed applications where integration, bandwidth and accuracy are essential. The HI5662 reaches a new level of multi-channel integration. The fully pipeline architecture and an innovative input stage enable the HI5662 to accept a variety of input configurations, single-ended or fully differential. Only one external clock is necessary to drive both converters and an internal band-gap voltage reference is provided. This allows the system designer to realize an increased level of system integration resulting in decreased cost and power dissipation.

The HI5662 has excellent dynamic performance while consuming only 650mW power at 60MSPS. The A/D only requires a single +5V power supply and encode clock. Data output latches are provided which present valid data to the output bus with a latency of 6 clock cycles.

For those customers needing dual channel 10-bit resolution, please refer to the HI5762. For single channel 10-bit applications, please refer to the HI5767.

Ordering Information

PART NUMBER	TEMP. RANGE (^{o}C)	PACKAGE	PKG. NO.
HI5662/6IN	-40 to 85	44 Ld MQFP	Q44.10x10
HI5662EVAL2	25	Evaluation Platform	

Features

- Sampling Rate 60MSPS
- 7.8 Bits at f_{IN} = 10MHz
- Low Power at 60MSPS. 650mW
- Wide Full Power Input Bandwidth. 250MHz
- Excellent Channel-to-Channel Isolation . . . . >75dB
- On-Chip Sample and Hold Amplifiers
- Internal Band-Gap Voltage Reference 2.5V
- Fully Differential or Single-Ended Analog Inputs
- Single Supply Voltage Operation . . . . +5V
- TTL/CMOS Compatible Digital Inputs
- CMOS Compatible Digital Outputs. 3.0/5.0V
- Offset Binary Digital Data Output Format
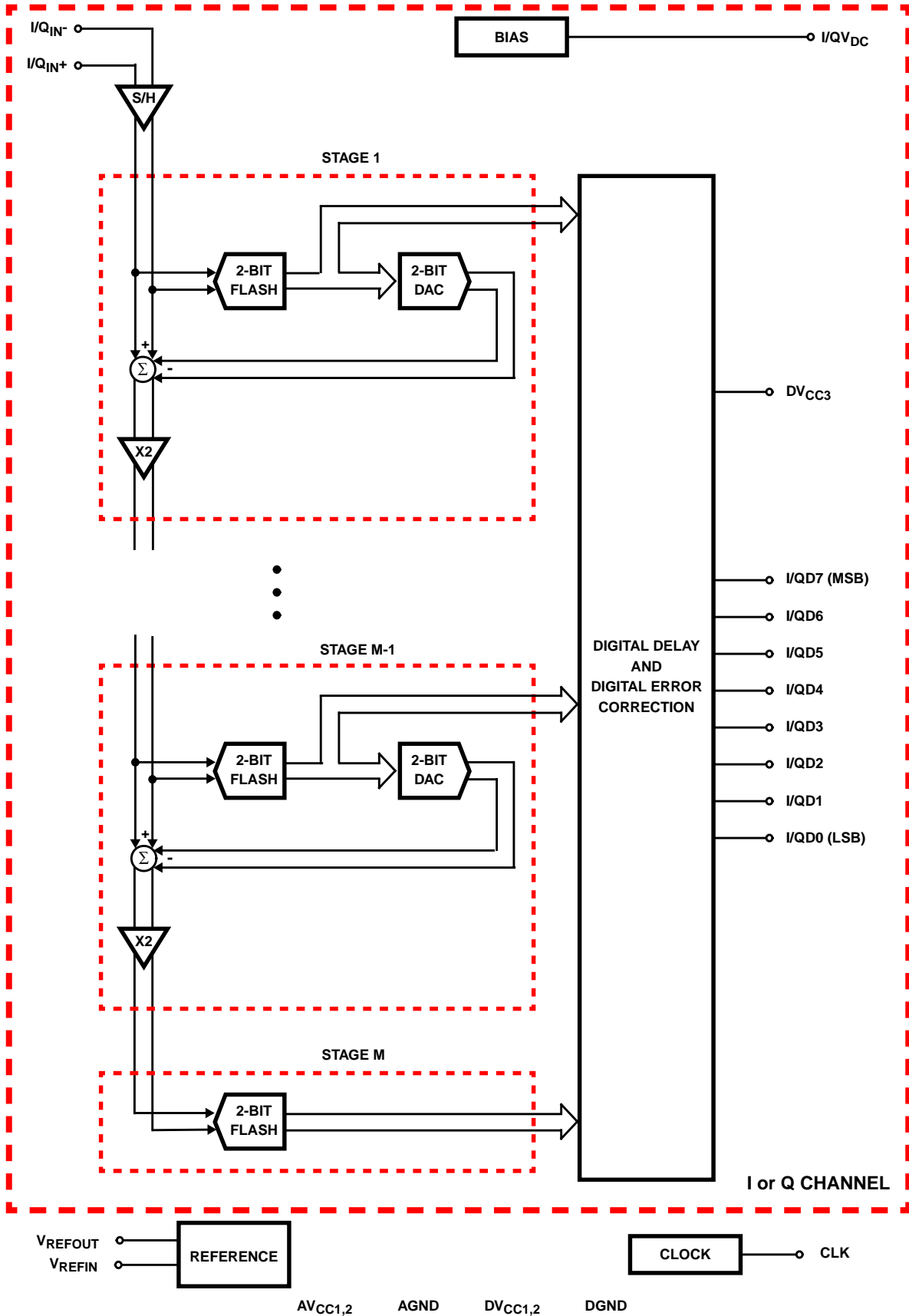- Dual 8-Bit A/D Converters on a Monolithic Chip

Applications

- Wireless Local Loop
- PSK and QAM I and Q Demodulators
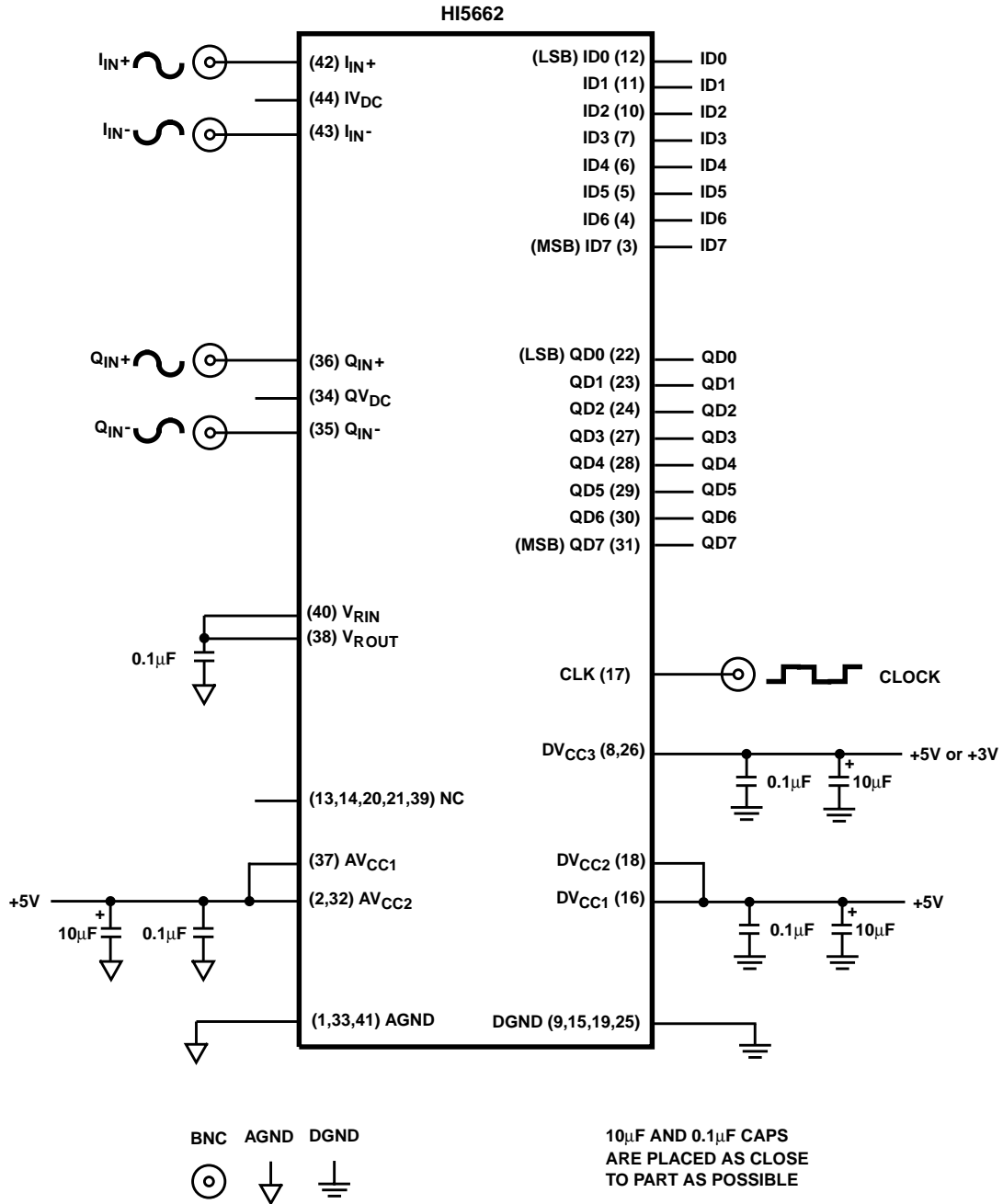- Medical Imaging
- High Speed Data Acquisition

Pinout

**HI5662
(MQFP)**
TOP VIEW
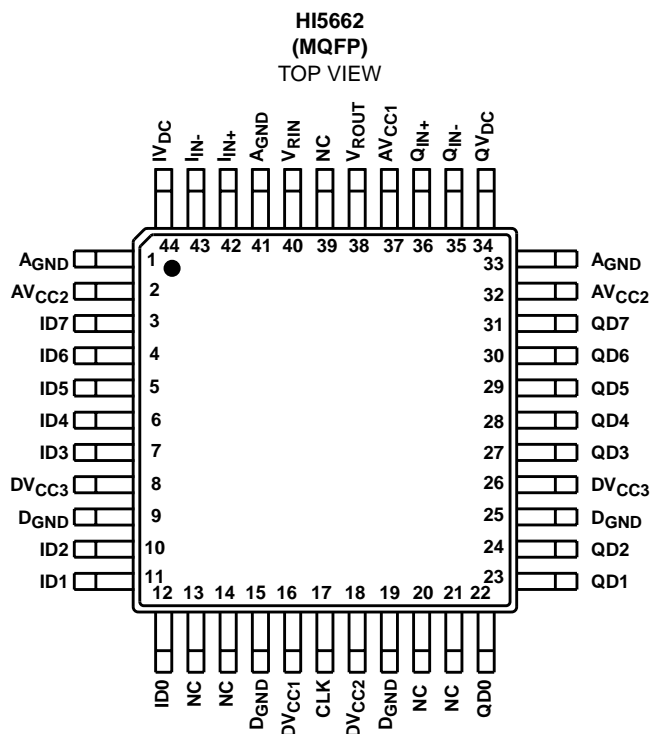
Functional Block Diagram

Typical Application Schematic

Pin Descriptions

PIN NO.	NAME	DESCRIPTION
1	A$_{GND}$	Analog Ground
2	AV$_{CC2}$	Analog Supply (+5.0V)
3	ID7	I-Channel, Data Bit 7 Output (MSB)
4	ID6	I-Channel, Data Bit 6 Output
5	ID5	I-Channel, Data Bit 5 Output
6	ID4	I-Channel Data Bit 4 Output
7	ID3	I-Channel, Data Bit 3 Output
8	DV$_{CC3}$	Digital Output Supply (+3.0V or +5.0V)
9	D$_{GND}$	Digital Ground
10	ID2	I-Channel, Data Bit 2 Output
11	ID1	I-Channel, Data Bit 1 Output
12	ID0	I-Channel, Data Bit 0 Output (LSB)
13	NC	No Connect
14	NC	No Connect
15	D$_{GND}$	Digital Ground
16	DV$_{CC1}$	Digital Supply (+5.0V)
17	CLK	Sample Clock Input
18	DV$_{CC2}$	Digital Supply (+5.0V)
19	D$_{GND}$	Digital Ground
20	NC	No Connect
21	NC	No Connect
22	QD0	Q-Channel, Data Bit 0 Output (LSB)
23	QD1	Q-Channel, Data Bit 1 Output

PIN NO.	NAME	DESCRIPTION
24	QD2	Q-Channel, Data Bit 2 Output
25	D$_{GND}$	Digital Ground
26	DV$_{CC3}$	Digital Output Supply (+3.0V or +5.0V)
27	QD3	Q-Channel, Data Bit 3 Output
28	QD4	Q-Channel, Data Bit 4 Output
29	QD5	Q-Channel, Data Bit 5 Output
30	QD6	Q-Channel, Data Bit 6 Output
31	QD7	Q-Channel, Data Bit 7 Output (MSB)
32	AV$_{CC2}$	Analog Supply (+5.0V)
33	A$_{GND}$	Analog Ground
34	QV$_{DC}$	Q-Channel DC Bias Voltage Output
35	Q$_{IN-}$	Q-Channel Negative Analog Input
36	Q$_{IN+}$	Q-Channel Positive Analog Input
37	AV$_{CC1}$	Analog Supply (+5.0V)
38	V$_{ROUT}$	+2.5V Reference Voltage Output
39	NC	No Connect
40	V$_{RIN}$	+2.5V Reference Voltage Input
41	A$_{GND}$	Analog Ground
42	I$_{IN+}$	I-Channel Positive Analog Input
43	I$_{IN-}$	I-Channel Negative Analog Input
44	IV$_{DC}$	I-Channel DC Bias Voltage Output

Absolute Maximum Ratings $T_A = 25^oC$

Supply Voltage, AV_{CC} or DV_{CC} to AGND or DGND 6V
DGND to AGND 0.3V
Digital I/O Pins . . . . DGND to DV_{CC}
Analog I/O Pins . . . . AGND to AV_{CC}

Operating Conditions

Temperature Range
    HI5662/6IN . . . . -40°C to 85°C

Thermal Information

Thermal Resistance (Typical, Note 1) θ_{JA} (^oC/W)
    HI5662/6IN   75
Maximum Junction Temperature . . . . .150°C
Maximum Storage Temperature Range . . . . -65°C to 150°C
Maximum Lead Temperature (Soldering 10s) . . . . .300°C
    (Lead Tips Only)

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

NOTE:

1. θ_{JA} is measured with the component mounted on an evaluation PC board in free air.

Electrical Specifications $AV_{CC1,2} = DV_{CC1,2} = +5.0V$, $DV_{CC3} = +3.0V$; $V_{RIN} = 2.50V$; $f_S = 60MSPS$ at 50% Duty Cycle;
$C_L = 10pF$; $T_A = 25^oC$; Differential Analog Input; Unless Otherwise Specified

| PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
ACCURACY					
Resolution		8	-	-	Bits
Integral Linearity Error, INL	$f_{IN} = 10MHz$	-	0.5	-	LSB
Differential Linearity Error, DNL (Guaranteed No Missing Codes)	$f_{IN} = 10MHz$	-	±0.2	±1.0	LSB
Offset Error, V_{OS}	$f_{IN} = DC$	-10	-	+10	LSB
Full Scale Error, FSE	$f_{IN} = DC$	-	1	-	LSB
DYNAMIC CHARACTERISTICS					
Minimum Conversion Rate	No Missing Codes	-	1	-	MSPS
Maximum Conversion Rate	No Missing Codes	60	-	-	MSPS
Effective Number of Bits, ENOB	$f_{IN} = 10MHz$ $f_{IN} = 10MHz$, Single Ended Analog Input	7.5 7.0	7.8 7.7	- -	Bits Bits
Signal to Noise and Distortion Ratio, SINAD $= \dfrac{\text{RMS Signal}}{\text{RMS Noise + Distortion}}$	$f_{IN} = 10MHz$	-	48.7	-	dB
Signal to Noise Ratio, SNR $= \dfrac{\text{RMS Signal}}{\text{RMS Noise}}$	$f_{IN} = 10MHz$	-	48	-	dB
Total Harmonic Distortion, THD	$f_{IN} = 10MHz$	-	-66	-	dBc
2nd Harmonic Distortion	$f_{IN} = 10MHz$	-	-71	-	dBc
3rd Harmonic Distortion	$f_{IN} = 10MHz$	-	-71	-	dBc
Spurious Free Dynamic Range, SFDR	$f_{IN} = 10MHz$	-	71	-	dBc
Intermodulation Distortion, IMD	$f_1 = 1MHz$, $f_2 = 1.02MHz$	-	64	-	dBc
I/Q Channel Crosstalk		-	-75	-60	dBc
I/Q Channel Offset Match		-	2.5	-	LSB
I/Q Channel Full Scale Error Match		-	2.5	-	LSB
Transient Response	(Note 2)	-	1	-	Cycle
Over-Voltage Recovery	0.2V Overdrive (Note 2)	-	1	-	Cycle

Electrical Specifications $AV_{CC1,2} = DV_{CC1,2} = +5.0V$, $DV_{CC3} = +3.0V$; $V_{RIN} = 2.50V$; $f_S = 60MSPS$ at 50% Duty Cycle; $C_L = 10pF$; $T_A = 25^oC$; Differential Analog Input; Unless Otherwise Specified **(Continued)**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
ANALOG INPUT					
Maximum Peak-to-Peak Differential Analog Input Range ($V_{IN}+ - V_{IN}-$)		-	±0.5	-	V
Maximum Peak-to-Peak Single-Ended Analog Input Range		-	1.0	-	V
Analog Input Resistance, R_{IN+} or R_{IN-}	V_{IN+}, V_{IN-} = VREF,DC	-	1	-	MΩ
Analog Input Capacitance, C_{IN+} or C_{IN-}	V_{IN+}, V_{IN-} = 2.5V,DC	-	10	-	pF
Analog Input Bias Current, I_B+ or I_B-	V_{IN+}, V_{IN-} = V_{REF-}, V_{REF+}, DC (Notes 2, 3)	-10	-	10	μA
Differential Analog Input Bias Current $I_{BDIFF} = (I_B+ - I_B-)$	(Notes 2, 3)	-0.5	-	+0.5	μA
Full Power Input Bandwidth, FPBW	(Note 2)	-	250	-	MHz
Analog Input Common Mode Voltage Range ($V_{IN}+ + V_{IN}-$) / 2	Differential Mode (Note 2)	0.25	-	4.75	V
INTERNAL VOLTAGE REFERENCE					
Reference Output Voltage, V_{ROUT} (Loaded)		2.35	2.5	2.65	V
Reference Output Current, I_{ROUT}		-	2	4	mA
Reference Temperature Coefficient		-	-400	-	ppm/^oC
REFERENCE VOLTAGE INPUT					
Reference Voltage Input, V_{RIN}		-	2.5	-	V
Total Reference Resistance, R_{RIN}	with V_{RIN} = 2.5V	-	1.25	-	kΩ
Reference Current, I_{RIN}	with V_{RIN} = 2.5V	-	2	-	mA
DC BIAS VOLTAGE					
DC Bias Voltage Output, V_{DC}		-	3.0	-	V
Maximum Output Current		-	-	0.4	mA
SAMPLING CLOCK INPUT					
Input Logic High Voltage, V_{IH}	CLK	2.0	-	-	V
Input Logic Low Voltage, V_{IL}	CLK	-	-	0.8	V
Input Logic High Current, I_{IH}	CLK, V_{IH} = 5V	-10.0	-	+10.0	μA
Input Logic Low Current, I_{IL}	CLK, V_{IL} = 0V	-10.0	-	+10.0	μA
Input Capacitance, C_{IN}	CLK	-	7	-	pF
DIGITAL OUTPUTS					
Output Logic High Voltage, V_{OH}	I_{OH} = 100μA; DV_{CC3} = 5V	4.0	-	-	V
Output Logic Low Voltage, V_{OL}	I_{OL} = 100μA; DV_{CC3} = 5V	-	-	0.8	V
Output Logic High Voltage, V_{OH}	I_{OH} = 100μA; DV_{CC3} = 3V	2.4	-	-	V
Output Logic Low Voltage, V_{OL}	I_{OL} = 100μA; DV_{CC3} = 3V	-	-	0.5	V
Output Capacitance, C_{OUT}		-	7	-	pF
TIMING CHARACTERISTICS					
Aperture Delay, t_{AP}		-	5	-	ns
Aperture Jitter, t_{AJ}		-	5	-	ps$_{RMS}$
Data Output Hold, t_H		-	10.7	-	ns

Electrical Specifications $AV_{CC1,2} = DV_{CC1,2} = +5.0V$, $DV_{CC3} = +3.0V$; $V_{RIN} = 2.50V$; $f_S = 60MSPS$ at 50% Duty Cycle; $C_L = 10pF$; $T_A = 25^{o}C$; Differential Analog Input; Unless Otherwise Specified **(Continued)**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
Data Output Delay, t_{OD}		-	11.7	-	ns
Data Latency, t_{LAT}	For a Valid Sample (Note 2)	6	6	6	Cycles
Power-Up Initialization	Data Invalid Time (Note 2)	-	-	20	Cycles
Sample Clock Pulse Width (Low)	(Note 2)	7.5	8.3	-	ns
Sample Clock Pulse Width (High)	(Note 2)	7.5	8.3	-	ns
Sample Clock Duty Cycle Variation			±5		%
POWER SUPPLY CHARACTERISTICS					
Analog Supply Voltage, AV_{CC}	(Note 2)	4.75	5.0	5.25	V
Digital Supply Voltage, DV_{CC1} and DV_{CC2}	(Note 2)	4.75	5.0	5.25	V
Digital Output Supply Voltage, DV_{CC3}	At 3.0V (Note 2)	2.7	3.0	3.3	V
	At 5.0V (Note 2)	4.75	5.0	5.25	V
Supply Current, I_{CC}	$f_S = 60MSPS$	-	130	-	mA
Power Dissipation		-	650	670	mW
Offset Error Sensitivity, ΔV_{OS}	AV_{CC} or $DV_{CC} = 5V \pm 5\%$	-	±0.125	-	LSB
Gain Error Sensitivity, ΔFSE	AV_{CC} or $DV_{CC} = 5V \pm 5\%$	-	±0.15	-	LSB

NOTES:

2. Parameter guaranteed by design or characterization and not production tested.

3. With the clock low and DC input.

Timing Waveforms
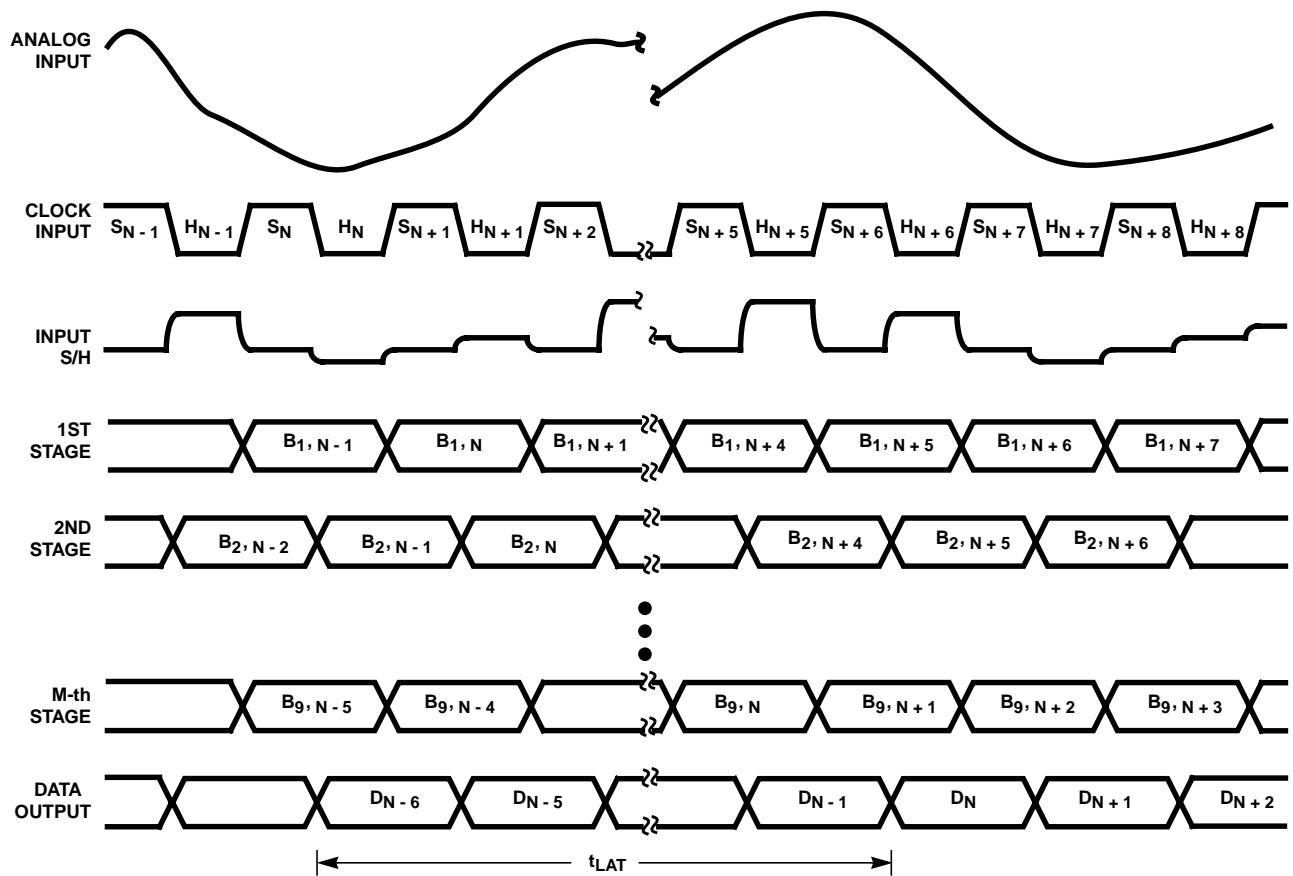
NOTES:

4. S_N: N-th sampling period.

5. H_N: N-th holding period.

6. $B_{M, N}$: M-th stage digital output corresponding to N-th sampled input.

7. D_N: Final data output corresponding to N-th sampled input.

FIGURE 1. HI5662 INTERNAL CIRCUIT TIMING
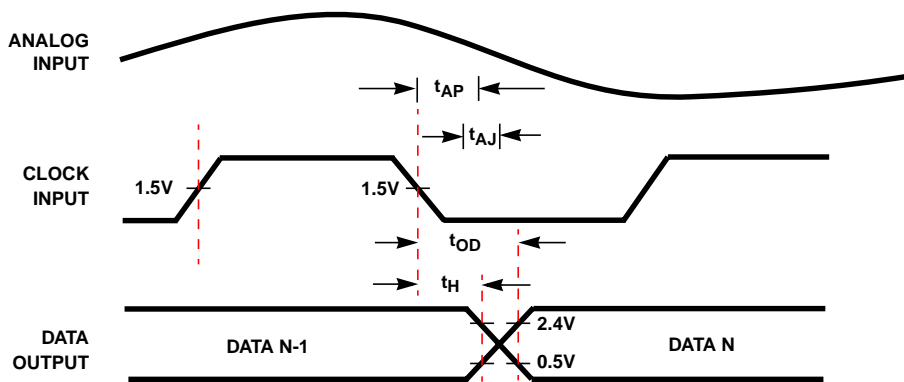
FIGURE 2. HI5662 INPUT-TO-OUTPUT TIMING

Typical Performance Curves
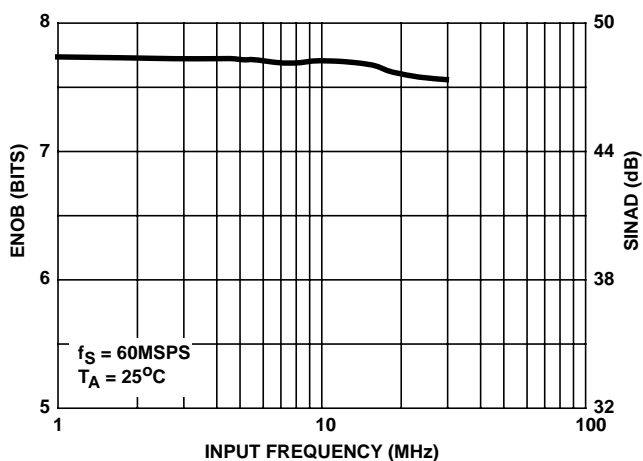
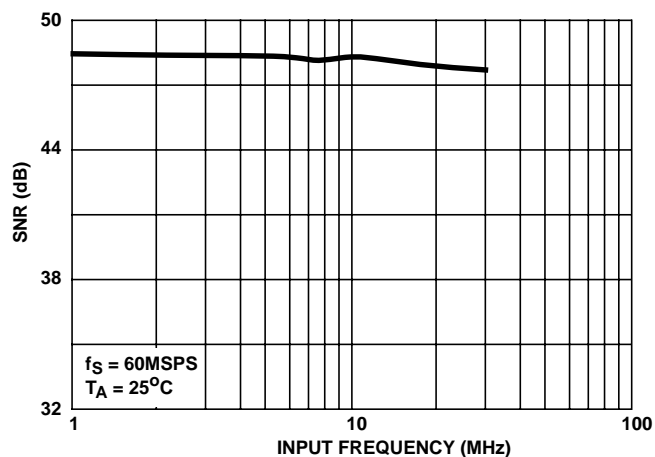FIGURE 3. EFFECTIVE NUMBER OF BITS (ENOB) AND SINAD vs INPUT FREQUENCY
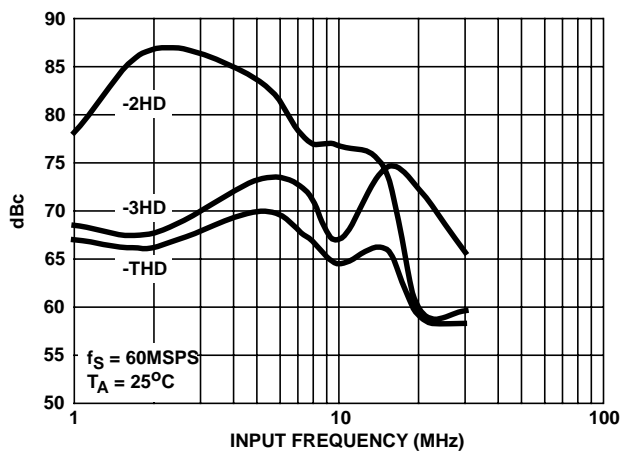

FIGURE 4. SNR vs INPUT FREQUENCY

FIGURE 5. -THD, -2HD AND -3HD vs INPUT FREQUENCY
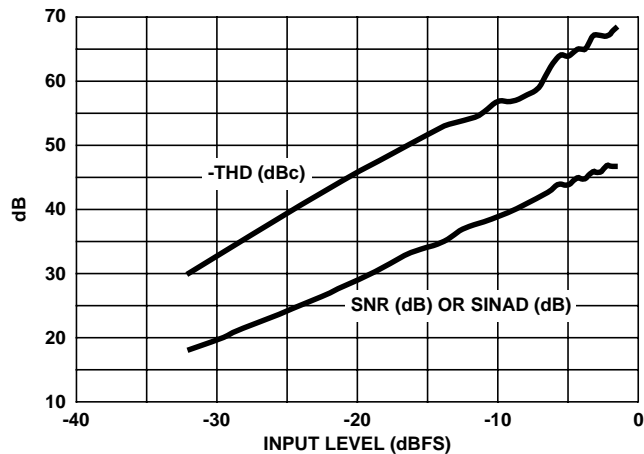
FIGURE 6. SINAD, SNR AND -THD vs INPUT AMPLITUDE
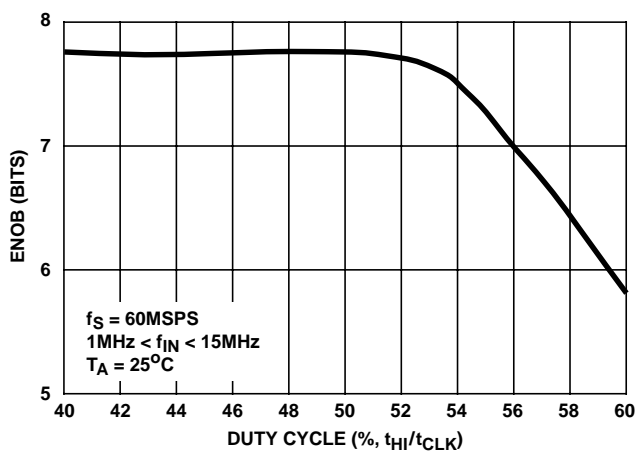
FIGURE 7. EFFECTIVE NUMBER OF BITS (ENOB) vs SAMPLE CLOCK DUTY CYCLE
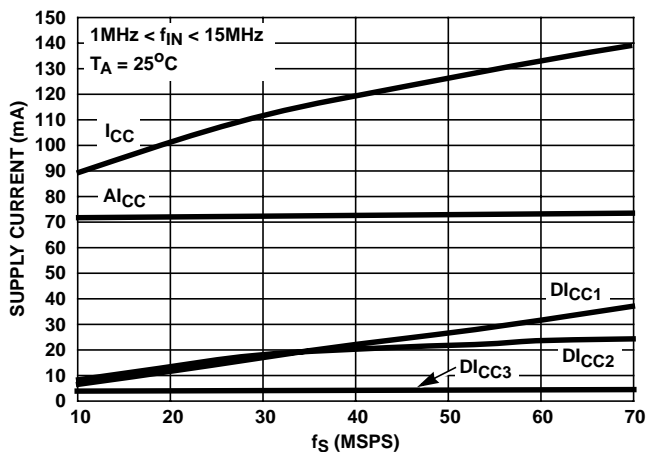
FIGURE 8. SUPPLY CURRENT vs SAMPLE CLOCK FREQUENCY

Typical Performance Curves (Continued)
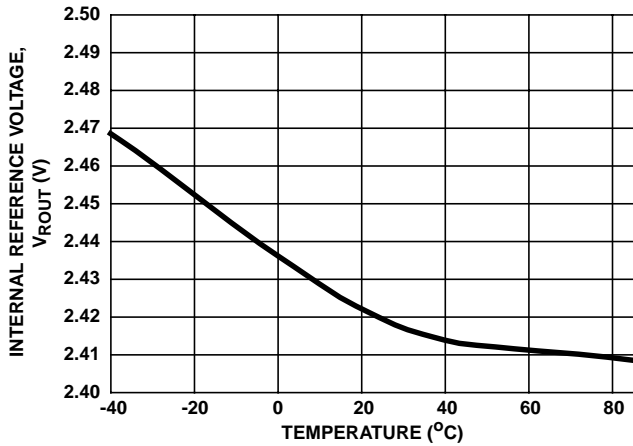
FIGURE 9. INTERNAL REFERENCE VOLTAGE (V_{ROUT}) vs TEMPERATURE
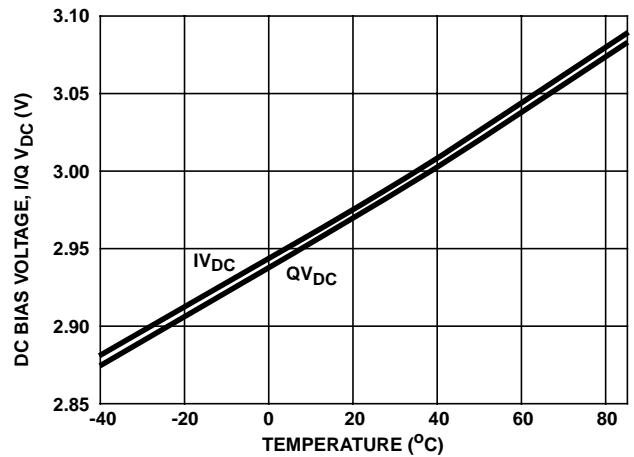
FIGURE 10. DC BIAS VOLTAGE (I/QVDC) vs TEMPERATURE
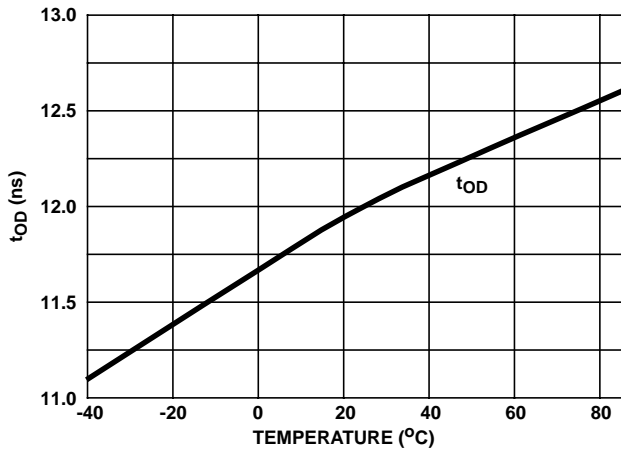
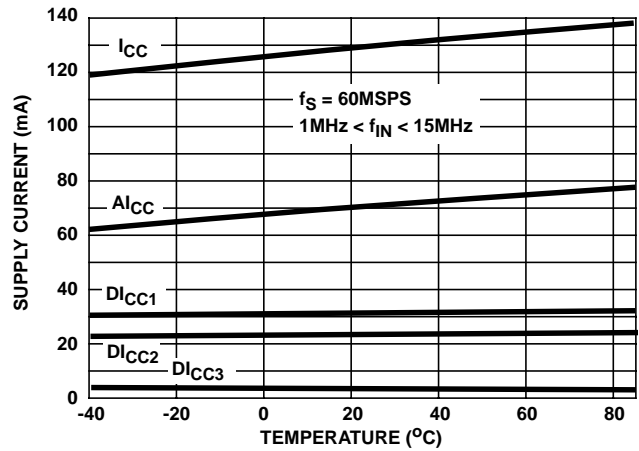FIGURE 11. DATA OUTPUT DELAY (t_{OD}) vs TEMPERATURE
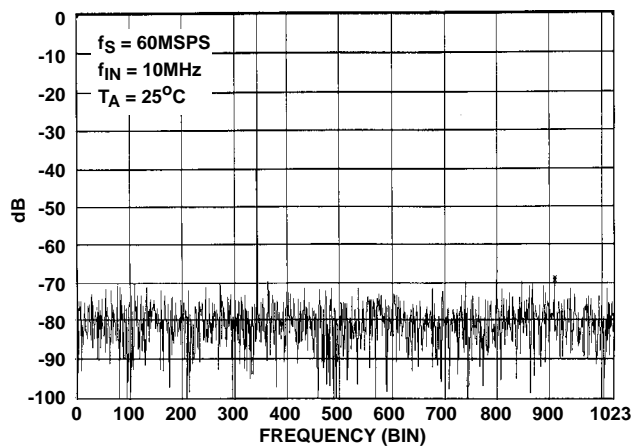

FIGURE 12. SUPPLY CURRENT vs TEMPERATURE

FIGURE 13. 2048 POINT FFT PLOT

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TABLE 1. A/D CODE TABLE

CODE CENTER DESCRIPTION	DIFFERENTIAL INPUT VOLTAGE (I/Q$_{IN}$+ - I/Q$_{IN}$-)	OFFSET BINARY OUTPUT CODE							
		MSB							LSB
		I/QD7	I/QD6	I/QD5	I/QD4	I/QD3	I/QD2	I/QD1	I/QD0
+Full Scale (+FS) -$^7/_{16}$LSB	0.498291V	1	1	1	1	1	1	1	1
+FS - 1$^7/_{16}$LSB	0.494385V	1	1	1	1	1	1	1	0
+$^9/_{16}$LSB	2.19727mV	1	0	0	0	0	0	0	0
-$^7/_{16}$LSB	-1.70898mV	0	1	1	1	1	1	1	1
-FS + 1$^9/_{16}$LSB	-0.493896V	0	0	0	0	0	0	0	1
-Full Scale (-FS) + $^9/_{16}$LSB	-0.497803V	0	0	0	0	0	0	0	0

NOTE:

8. The voltages listed above represent the ideal center of each output code shown with V$_{REFIN}$ = +2.5V.

Detailed Description

Theory of Operation

The HI5662 is a dual 8-bit fully differential sampling pipeline A/D converter with digital error correction logic. Figure 14 depicts the circuit for the front end differential-in-differential-out sample-and-hold (S/H) amplifiers. The switches are controlled by an internal sampling clock which is a non-overlapping two phase signal, ϕ_1 and ϕ_2, derived from the master sampling clock. During the sampling phase, ϕ_1, the input signal is applied to the sampling capacitors, C$_S$. At the same time the holding capacitors, C$_H$, are discharged to analog ground. At the falling edge of ϕ_1 the input signal is sampled on the bottom plates of the sampling capacitors. In the next clock phase, ϕ_2, the two bottom plates of the sampling capacitors are connected together and the holding capacitors are switched to the op-amp output nodes. The charge then redistributes between C$_S$ and C$_H$ completing one sample-and-hold cycle. The front end sample-and-hold output is a fully-differential, sampled-data representation of the analog input. The circuit not only performs the sample-and-hold function but will also convert a single-ended input to a fully-differential output for the converter core. During the sampling phase, the I/Q$_{IN}$ pins see only the on-resistance of a switch and C$_S$. The relatively small values of these components result in a typical full power input bandwidth of 250MHz for the converter.
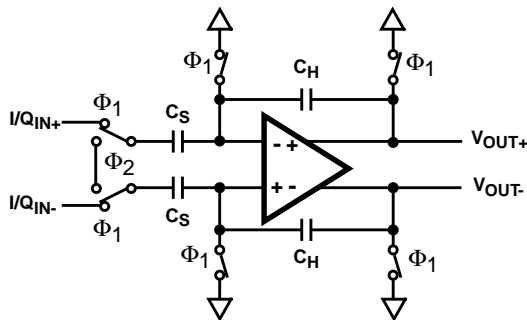

FIGURE 14. ANALOG INPUT SAMPLE-AND-HOLD

As illustrated in the functional block diagram and the timing diagram in Figure 1, identical pipeline subconverter stages, each containing a two-bit flash converter and a two-bit multiplying digital-to-analog converter, follow the S/H circuit with the last stage being a two bit flash converter. Each converter stage in the pipeline will be sampling in one phase and amplifying in the other clock phase. Each individual subconverter clock signal is offset by 180 degrees from the previous stage clock signal resulting in alternate stages in the pipeline performing the same operation.

The output of each of the identical two-bit subconverter stages is a two-bit digital word containing a supplementary bit to be used by the digital error correction logic. The output of each subconverter stage is input to a digital delay line which is controlled by the internal sampling clock. The function of the digital delay line is to time align the digital outputs of the identical two-bit subconverter stages with the corresponding output of the last stage flash converter before applying the results to the digital error correction logic. The digital error correction logic uses the supplementary bits to correct any error that may exist before generating the final eight bit digital data output of the converter.

Because of the pipeline nature of this converter, the digital data representing an analog input sample is output to the digital data bus following the 6th cycle of the clock after the analog sample is taken (see the timing diagram in Figure 1). This time delay is specified as the data latency. After the data latency time, the digital data representing each succeeding analog sample is output during the following clock cycle. The digital output data is provided in offset binary format (see Table 1, A/D Code Table).

Internal Reference Voltage Output, V$_{REFOUT}$

The HI5662 is equipped with an internal reference voltage generator, therefore, no external reference voltage is required. V$_{ROUT}$ must be connected to V$_{RIN}$ when using the internal reference voltage.

An internal band-gap reference voltage followed by an amplifier/buffer generates the precision +2.5V reference voltage used by the converter. A band-gap reference circuit is used to generate a precision +1.25V internal reference voltage. This voltage is then amplified by a wide-band uncompensated operational amplifier connected in a gain-of-two configuration. An external, user-supplied, 0.1μF capacitor connected from the V_{ROUT} output pin to analog ground is used to set the dominant pole and to maintain the stability of the operational amplifier.

Reference Voltage Input, V_{REFIN}

The HI5662 is designed to accept a +2.5V reference voltage source at the V_{RIN} input pin. Typical operation of the converter requires V_{RIN} to be set at +2.5V. The HI5662 is tested with V_{RIN} connected to V_{ROUT} yielding a fully differential analog input voltage range of ±0.5V.

The user does have the option of supplying an external +2.5V reference voltage. As a result of the high input impedance presented at the V_{RIN} input pin, 1.25kΩ typically, the external reference voltage being used is only required to source 2mA of reference input current. In the situation where an external reference voltage will be used an external 0.1μF capacitor **must** be connected from the V_{ROUT} output pin to analog ground in order to maintain the stability of the internal operational amplifier.

In order to minimize overall converter noise it is recommended that adequate high frequency decoupling be provided at the reference voltage input pin, V_{RIN}.

Analog Input, Differential Connection

The analog input of the HI5662 is a differential input that can be configured in various ways depending on the signal source and the required level of performance. A fully differential connection (Figure 15 and Figure 16) will deliver the best performance from the converter.
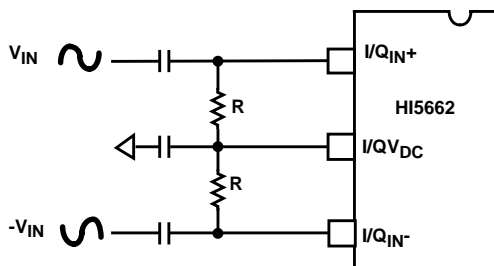

FIGURE 15. AC COUPLED DIFFERENTIAL INPUT

Since the HI5662 is powered by a single +5V analog supply, the analog input is limited to be between ground and +5V. For the differential input connection this implies the analog input common mode voltage can range from 0.25V to 4.75V. The performance of the ADC does not change significantly with the value of the analog input common mode voltage.

A DC voltage source, I/QV$_{DC}$, equal to 3.0V (typical), is made available to the user to help simplify circuit design when using

an AC coupled differential input. This low output impedance voltage source is not designed to be a reference but makes an excellent DC bias source and stays well within the analog input common mode voltage range over temperature.

For the AC coupled differential input (Figure 15) and with V_{RIN} connected to V_{ROUT}, full scale is achieved when the V_{IN} and -V_{IN} input signals are 0.5V$_{P-P}$, with -V_{IN} being 180 degrees out of phase with V_{IN}. The converter will be at positive full scale when the I/Q$_{IN+}$ input is at V_{DC} + 0.25V and the I/Q$_{IN-}$ input is at V_{DC} - 0.25V (I/Q$_{IN+}$ - I/Q$_{IN-}$ = +0.5V). Conversely, the converter will be at negative full scale when the I/Q$_{IN+}$ input is equal to V_{DC} - 0.25V and I/Q$_{IN-}$ is at V_{DC} + 0.25V (I/Q$_{IN+}$ - I/Q$_{IN-}$ = -0.5V).

The analog input can be DC coupled (Figure 16) as long as the inputs are within the analog input common mode voltage range (0.25V ≤ VDC ≤ 4.75V).
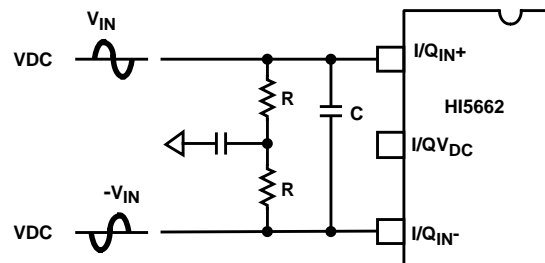

FIGURE 16. DC COUPLED DIFFERENTIAL INPUT

The resistors, R, in Figure 16 are not absolutely necessary but may be used as load setting resistors. A capacitor, C, connected from I/Q$_{IN+}$ to I/Q$_{IN-}$ will help filter any high frequency noise on the inputs, also improving performance. Values around 20pF are sufficient and can be used on AC coupled inputs as well. Note, however, that the value of capacitor C chosen must take into account the highest frequency component of the analog input signal.

Analog Input, Single-Ended Connection

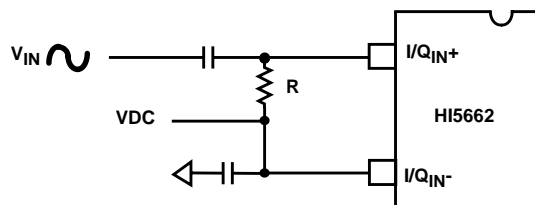The configuration shown in Figure 17 may be used with a single ended AC coupled input.

FIGURE 17. AC COUPLED SINGLE ENDED INPUT

Again, with V_{RIN} connected to V_{ROUT}, if V_{IN} is a 1V$_{P-P}$ sinewave, then I/Q$_{IN+}$ is a 1.0V$_{P-P}$ sinewave riding on a positive voltage equal to V_{DC}. The converter will be at positive full scale when I/Q$_{IN+}$ is at V_{DC} + 0.5V (I/Q$_{IN+}$ - I/Q$_{IN-}$ = +0.5V) and will be at negative full scale when I/Q$_{IN+}$ is equal to V_{DC} - 0.5V (I/Q$_{IN+}$ - I/Q$_{IN-}$ = -0.5V). Sufficient headroom must be provided such that the input voltage never goes above +5V

or below AGND. In this case, VDC could range between 0.5V and 4.5V without a significant change in ADC performance. The simplest way to produce VDC is to use the DC bias source, I/QV_{DC}, of the HI5662.

The single ended analog input can be DC coupled (Figure 18) as long as the input is within the analog input common mode voltage range.
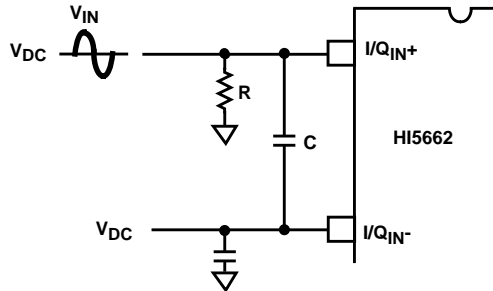

FIGURE 18. DC COUPLED SINGLE ENDED INPUT

The resistor, R, in Figure 18 is not absolutely necessary but may be used as a load setting resistor. A capacitor, C, connected from $I/Q_{IN}+$ to $I/Q_{IN}-$ will help filter any high frequency noise on the inputs, also improving performance. Values around 20pF are sufficient and can be used on AC coupled inputs as well. Note, however, that the value of capacitor C chosen must take into account the highest frequency component of the analog input signal.

A single ended source may give better overall system performance if it is first converted to differential before driving the HI5662.

Sampling Clock Requirements

The HI5662 sampling clock input provides a standard high-speed interface to external TTL/CMOS logic families.

In order to ensure rated performance of the HI5662, the duty cycle of the clock should be held at 50% ±5%. It must also have low jitter and operate at standard TTL/CMOS levels.

Performance of the HI5662 will only be guaranteed at conversion rates above 1MSPS (Typ). This ensures proper performance of the internal dynamic circuits. Similarly, when power is first applied to the converter, a maximum of 20 cycles at a sample rate above 1MSPS must to be performed before valid data is available.

Supply and Ground Considerations

The HI5662 has separate analog and digital supply and ground pins to keep digital noise out of the analog signal path. The digital data outputs also have a separate supply pin, DV_{CC3}, which can be powered from a 3.0V or 5.0V supply. This allows the outputs to interface with 3.0V logic if so desired.

The part should be mounted on a board that provides separate low impedance connections for the analog and digital supplies and grounds. For best performance, the supplies to the HI5662 should be driven by clean, linear

regulated supplies. The board should also have good high frequency decoupling capacitors mounted as close as possible to the converter. If the part is powered off a single supply then the analog supply can be isolated by a ferrite bead from the digital supply.

Refer to the application note "Using Intersil High Speed A/D Converters" (AN9214) for additional considerations when using high speed converters.

Static Performance Definitions

Offset Error (V_{OS})

The midscale code transition should occur at a level $^1/_4$LSB above half-scale. Offset is defined as the deviation of the actual code transition from this point.

Full-Scale Error (FSE)

The last code transition should occur for an analog input that is $^3/_4$LSB below Positive Full Scale (+FS) with the offset error removed. Full scale error is defined as the deviation of the actual code transition from this point.

Differential Linearity Error (DNL)

DNL is the worst case deviation of a code width from the ideal value of 1LSB.

Integral Linearity Error (INL)

INL is the worst case deviation of a code center from a best fit straight line calculated from the measured data.

Power Supply Sensitivity

Each of the power supplies are moved plus and minus 5% and the shift in the offset and full scale error (in LSBs) is noted.

Dynamic Performance Definitions

Fast Fourier Transform (FFT) techniques are used to evaluate the dynamic performance of the HI5662. A low distortion sine wave is applied to the input, it is coherently sampled, and the output is stored in RAM. The data is then transformed into the frequency domain with an FFT and analyzed to evaluate the dynamic performance of the A/D. The sine wave input to the part is typically -0.5dB down from full scale for all these tests.

SNR and SINAD are quoted in dB. The distortion numbers are quoted in dBc (decibels with respect to carrier) and **DO NOT** include any correction factors for normalizing to full scale.

The Effective Number of Bits (ENOB) is calculated from the SINAD data by:

ENOB = (SINAD - 1.76 + V_{CORR}) / 6.02,

where: V_{CORR} = 0.5 dB (Typical).

V_{CORR} adjusts the SINAD, and hence the ENOB, for the amount the analog input signal is backed off from full scale.

Signal To Noise and Distortion Ratio (SINAD)

SINAD is the ratio of the measured RMS signal to RMS sum of all the other spectral components below the Nyquist frequency, $f_S/2$, excluding DC.

Signal To Noise Ratio (SNR)

SNR is the ratio of the measured RMS signal to RMS noise at a specified input and sampling frequency. The noise is the RMS sum of all of the spectral components below $f_S/2$ excluding the fundamental, the first five harmonics and DC.

Total Harmonic Distortion (THD)

THD is the ratio of the RMS sum of the first 5 harmonic components to the RMS value of the fundamental input signal.

2nd and 3rd Harmonic Distortion

This is the ratio of the RMS value of the applicable harmonic component to the RMS value of the fundamental input signal.

Spurious Free Dynamic Range (SFDR)

SFDR is the ratio of the fundamental RMS amplitude to the RMS amplitude of the next largest spectral component in the spectrum below $f_S/2$.

Intermodulation Distortion (IMD)

Nonlinearities in the signal path will tend to generate intermodulation products when two tones, f_1 and f_2, are present at the inputs. The ratio of the measured signal to the distortion terms is calculated. The terms included in the calculation are (f_1+f_2), (f_1-f_2), $(2f_1)$, $(2f_2)$, $(2f_1+f_2)$, $(2f_1-f_2)$, (f_1+2f_2), (f_1-2f_2). The ADC is tested with each tone 6dB below full scale.

Transient Response

Transient response is measured by providing a full-scale transition to the analog input of the ADC and measuring the number of cycles it takes for the output code to settle within 10-bit accuracy.

Over-Voltage Recovery

Over-Voltage Recovery is measured by providing a full-scale transition to the analog input of the ADC which overdrives the input by 200mV, and measuring the number of cycles it takes for the output code to settle within 10-bit accuracy.

Full Power Input Bandwidth (FPBW)

Full power input bandwidth is the analog input frequency at which the amplitude of the digitally reconstructed output has decreased 3dB below the amplitude of the input sine wave. The input sine wave has an amplitude which swings from -FS to +FS. The bandwidth given is measured at the specified sampling frequency.

I/Q Channel Crosstalk

I/Q Channel Crosstalk is a measure of the amount of channel separation or isolation between the two A/D converter cores contained within the dual converter package. The measurement consists of stimulating one channel of the converter with a fullscale input signal and then measuring the amount that signal is below, in dBc, a fullscale signal on the opposite channel.

Timing Definitions

Refer to Figure 1 and Figure 2 for these definitions.

Aperture Delay (t_{AP})

Aperture delay is the time delay between the external sample command (the falling edge of the clock) and the time at which the signal is actually sampled. This delay is due to internal clock path propagation delays.

Aperture Jitter (t_{AJ})

Aperture jitter is the RMS variation in the aperture delay due to variation of internal clock path delays.

Data Hold Time (t_H)

Data hold time is the time to where the previous data (N - 1) is no longer valid.

Data Output Delay Time (t_{OD})

Data output delay time is the time to where the new data (N) is valid.

Data Latency (t_{LAT})

After the analog sample is taken, the digital data representing an analog input sample is output to the digital data bus following the 6th cycle of the clock after the analog sample is taken. This is due to the pipeline nature of the converter where the analog sample has to ripple through the internal subconverter stages. This delay is specified as the data latency. After the data latency time, the digital data representing each succeeding analog sample is output during the following clock cycle. The digital data lags the analog input sample by 6 sample clock cycles.

Power-Up Initialization

This time is defined as the maximum number of clock cycles that are required to initialize the converter at power-up. The requirement arises from the need to initialize the dynamic circuits within the converter.

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