## Features

- $256 \times 256$ or $512 \times 256$ switching configurations
- 8 -bit or 4 -bit channel switching capability
- Guarantees frame integrity for wideband channels
- Automatic identification of ST-BUS/GCI interfaces
- Accepts serial streams with data rates up to 8.192 Mb/s
- Rate conversion from $2.048 \mathrm{Mb} / \mathrm{s}$ to 4.096 or $8.192 \mathrm{Mb} / \mathrm{s}$ and vice-versa
- Programmable frame offset on inputs
- Per-channel three-state control
- Per-channel message mode
- Control interface compatible to Intel/Motorola CPUs
- Low power consumption


## Applications

- Medium size digital switch matrices
- Hyperchannel switching (e.g., ISDN H0)
- MVIP ${ }^{\text {TM }}$ interface functions
- Serial bus control and monitoring
- Centralized voice processing systems
- Voice/Data multiplexer
- $32 \mathrm{kbit} / \mathrm{s}$ channel switching

February 2005

| Ordering Information |  |  |
| :---: | :---: | :---: |
| MT7986AE | 40 Pin PDIP | Tubes |
| MT8986AP | 44 Pin PLCC | Tubes |
| MT8986AL | 44 Pin MQFP |  |
| MT8986APR | ${ }_{44}^{44}$ Pin PLCC | Tape \& Reel |
| MT8986AP1 | 44 Pin PLCC** | Tubes |
| MT8986APR1 | 44 Pin PLCC* | Tape \& Reel |
|  | *Pb Free Matte Tin |  |
| $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  |  |

## Description

The Multiple Rate Digital Switch (MRDX) is an upgraded version of Zarlink's MT8980D Digital Switch (DX). It is pin compatible with the MT8980D and retains all of its functionality. This device is designed to provide simultaneous connections (non-blocking) for up to $25664 \mathrm{~kb} / \mathrm{s}$ channels or blocking connections for up to $51264 \mathrm{~kb} / \mathrm{s}$ channels. The serial inputs and outputs connected to MT8986 may have 32 to 128 $64 \mathrm{~kb} / \mathrm{s}$ channels per frame with data rates ranging from 2048 up to $8192 \mathrm{~kb} / \mathrm{s}$. The MT8986 provides perchannel selection between variable and constant throughput delays allowing voice and grouped data channels to be switched without corrupting the data sequence integrity.

In addition, the MT8986 can be used for switching of $32 \mathrm{~kb} / \mathrm{s}$ channels in ADPCM applications. The MT8986 is ideal for medium size mixed voice and data switching/processing applications.


Figure 1 - Functional Block Diagram


Figure 2 - Pin Connections

## Pin Description

| Pin \# |  |  | Name | Description |
| :---: | :---: | :---: | :---: | :---: |
| $\underset{\text { DIP }}{40}$ | $\stackrel{44}{\text { PLCC }}$ | $\stackrel{44}{\text { QFP }}$ |  |  |
| 1 | 2 | 40 | $\overline{\text { DTA }}$ | Data Acknowledgement (Open Drain Output). This active low output indicates that a data bus transfer is complete. A $10 \mathrm{k} \Omega$ pull-up resistor is required at this output. |
| 2-7 | $\begin{aligned} & 3-5 \\ & 7-9 \end{aligned}$ | $\begin{gathered} 41-43 \\ 1-3 \end{gathered}$ | STi0-5 | ST-BUS Inputs 0 to 5 (Inputs). Serial data input streams. These streams may have data rates of $2.048,4.096$ or $8.192 \mathrm{Mbit} / \mathrm{s}$ with 32,64 or 128 channels, respectively. |
| 8 | 10 | 4 | STi6/A6 | ST-BUS Input 6/Addr. 6 input (Input). The function of this pin is determined by the switching configuration enabled. If non-multiplexed CPU bus is used along with a higher input rate of 8.192 or $4.096 \mathrm{Mb} / \mathrm{s}$, this pin provides A 6 address input function. For 2.048 and $4.096 \mathrm{Mb} / \mathrm{s}(8 \times 4)$ applications or when multiplexed CPU bus ( 44 pin only) is selected, this pin assumes STi6 function. See Control Register bits description and Tables 1, 2, 6 \& 7 for more details. Note that for applications where both A6 and STi6 inputs are required simultaneously (e.g., $8 \times 4$ switching configuration at $4.096 \mathrm{Mb} / \mathrm{s}$ or rate conversion between $2.048 \mathrm{Mb} / \mathrm{s}$ to 4.196 or $8.192 \mathrm{Mb} / \mathrm{s}$ ) the A 6 input should be connected to pin STo6/A6. |
| 9 | 11 | 5 | STi7/A7 | ST-BUS Input 7/Addr. 7 input (Input): The function of this pin is determined by the switching configuration enabled. If non-multiplexed CPU bus is used along with a higher input rate of $8.192 \mathrm{Mb} / \mathrm{s}$, this pin provides A 7 address input function. <br> For 2.048 and $4.096 \mathrm{Mb} / \mathrm{s}(8 \times 4)$ applications or when multiplexed CPU bus (44 pin only) is selected, this pin assumes STi7 function. See Control Register bits description and Tables 1, 2, 6 \& 7 for more details. <br> Note that for applications where both A7 and STi7 inputs are required simultaneously (e.g., 2.048 to $8.192 \mathrm{Mb} / \mathrm{s}$ rate conversion) the A7 input should be connected to pin STo7/A7. |
| 10 | 12 | 6 | $\mathrm{V}_{\text {DD }}$ | +5 Volt Power Supply. |
| 11 | 13 | 7 | FR | Frame Pulse (Input). This input accepts and automatically identifies frame synchronization signals formatted according to ST-BUS and GCI interface specifications. |
| 12 | 14 | 8 | CLK | Clock (Input). Serial clock for shifting data in/out on the serial streams. Depending on the serial interface speed selected by IMS (Interface Mode Select) register, the clock at this pin can be 4.096 or 8.192 MHz . |
| 13-15 | 15-17 | 9-11 | $\begin{gathered} \text { A0-2/ } \\ \text { STi8-10 } \end{gathered}$ | Address 0-2 / Input Streams 8-10 (Input). When non-multiplexed CPU bus is selected, these lines provide the A0-A2 address lines to MT8986 internal registers. When $16 \times 8$ switching configuration is selected (in 44 pin only), then these pins are ST-BUS serial inputs 8 to 10 receiving data at $2.048 \mathrm{Mb} / \mathrm{s}$. |
| 16-18 | 19-21 | 13-15 | $\begin{gathered} \text { A3-5/ } \\ \text { STi11-13 } \end{gathered}$ | Address 3-5 / Input Streams 11-13 (Input). When non-multiplexed CPU bus is selected, these lines provide the A3-A5 address lines to MT8986 internal registers. When $16 \times 8$ switching configuration is selected (in 44 pin only), then these pins are ST-BUS serial inputs 11 to 13 receiving data at $2.048 \mathrm{Mb} / \mathrm{s}$. |

## Pin Description (continued)

| Pin \# |  |  | Name | Description |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 40 \\ \text { DIP } \end{gathered}$ | $\begin{gathered} 44 \\ \text { PLCC } \end{gathered}$ | $\stackrel{44}{\text { QFP }}$ |  |  |
| 19 | 22 | 16 | DS/ $\overline{\mathbf{R D}}$ | Data Strobe/Read (Input). When non-multiplexed CPU bus or Motorola multiplexed bus (44 pin only) are selected, this input is DS. This active high input works in conjunction with $\overline{C S}$ to enable read and write operation. <br> For Intel/National multiplexed bus ( 44 pin only), this input is $\overline{\mathrm{RD}}$. This active low input configures the data bus lines (AD0-AD7) as outputs. |
| 20 | 23 | 17 | $\mathbf{R} / \overline{\mathbf{W}} \overline{\mathbf{W R}}$ | Read/Write \Write (Input). In case of non-multiplexed and Motorola multiplexed buses (44 pin only), this input is $R / \bar{W}$. This input controls the direction of the data bus lines (AD0-AD7) during a microprocessor access. <br> With Intel/National multiplexed timing (44 pin only), this input is $\overline{W R}$. This active low signal configures the data bus lines (AD0-AD7) as inputs. |
| 21 | 24 | 18 | $\overline{\mathrm{CS}}$ | Chip Select (Input). Active low input enabling a microprocessor read or write of the control register or internal memories. |
| 22-29 | $\begin{array}{\|l\|} \hline 25-27 \\ \mathbf{2 9 - 3 3} \end{array}$ | $\begin{aligned} & 19-21 \\ & 23-27 \end{aligned}$ | $\begin{aligned} & \text { AD7- } \\ & \text { AD0 } \end{aligned}$ | Data Bus (Bidirectional): These pins provide microprocessor access to the internal control registers, connection memories high and low and data memories. In multiplexed bus mode (44 pin) these pins also provide the input address to the internal Address Latch circuit. |
| 30 | 34 | 28 | $\mathbf{V}_{\text {SS }}$ | Ground. |
| 31 | 35 | 29 | STo7/A7 | ST-BUS Output 7/Address 7 input (Three-state output/input). The function of this pin is determined by the switching configuration enabled. If non-multiplexed CPU bus is used along with data rates employing $8.192 \mathrm{Mb} / \mathrm{s}$ rates, this pin provides A7 address input function. For $2.048 \mathrm{Mb} / \mathrm{s}$ applications or when multiplexed CPU bus (44 pin only) is selected, this pin assumes STo7 function. See Tables 1, 2, 6 \& 7 for more details. <br> Note that for applications where A7 input and STo7 output are required simultaneously (e.g., 8.192 to $2.048 \mathrm{Mb} /$ s rate conversion), the A7 input should be connected to pin STi7/A7. |
| 32 | 36 | 30 | STo6/A6 | ST-BUS Output 6/Address 6 input (Three-state output/input). The function of this pin is determined by the switching configuration enabled. If non-multiplexed CPU bus is used along with a higher data rate employing 8.192 or $4.096 \mathrm{Mb} / \mathrm{s}$, this pin provides the A6 address input function. For $2.048 \mathrm{Mb} / \mathrm{s}$ applications or when multiplexed CPU bus (44 pin only) is selected, this pin assumes STo6 function. See Tables 1, 2, 6 \& 7 for more details. <br> Note that for applications where both A6 input and STo6 output are required simultaneously (e.g., 4.096 to $2.048 \mathrm{Mb} / \mathrm{s}$ or 8.192 to $2.048 \mathrm{Mb} / \mathrm{s}$ rate conversion applications), the A6 input should be connected to pin STi6/A6. |
| 33-38 | $\begin{array}{\|l\|} \hline 37-39 \\ 41-43 \end{array}$ | $\begin{aligned} & \mathbf{3 1 - 3 3} \\ & \mathbf{3 5 - 3 7} \end{aligned}$ | STo5-0 | ST-BUS Outputs 5 to 0 (Three-state Outputs). Serial data output streams. These serial streams may be composed of 32,64 and 128 channels at data rates of $2.048,4.096$ or $8.192 \mathrm{Mbit} / \mathrm{s}$, respectively. |
| 39 | 44 | 38 | ODE | Output Drive Enable (Input). This is the output enable input for the STo0 to STo9 serial outputs. If this input is low STo0-9 are high impedance. If this input is high each channel may still be put into high impedance by using per-channel control bits in Connect Memory High. |

## Pin Description (continued)

| Pin \# |  |  | Name | Description |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 40 \\ \text { DIP } \end{gathered}$ | $\stackrel{44}{\text { PLCC }}$ | $\stackrel{44}{\mathrm{QFP}}$ |  |  |
| 40 | 1 | 39 | CSTo | Control ST-BUS Output (Output). This is a $2.048 \mathrm{Mb} / \mathrm{s}$ output containing 256 bits per frame. The level of each bit is determined by the CSTo bit in the Connect Memory high locations. |
| - | 6 | 44 | AS/ALE | Address Strobe or Latch Enable (Input). This input is only used if multiplexed bus is selected via the IM input pin (44 pin only). <br> The falling edge of this signal is used to sample the address into the address latch circuit. In case of non-multiplexed bus, this input is not required and should be left open. |
| - | 18 | 12 | IM | CPU Interface Mode (Input). If HIGH, this input configures MT8986 in multiplexed microprocessor bus mode. If this input pin is not connected or grounded, the MT8986 assumes non-multiplexed CPU interface. |
| - | 28 | 22 | $\begin{aligned} & \hline \text { STi15/ } \\ & \text { ST09 } \end{aligned}$ | ST-BUS Input 15 / ST-BUS Output 9 (Input/three-state output). This pin is only used if multiplexed CPU bus is selected. If 16 -input $x 8$-output switching configuration is enabled in the SCB bits (IMS register), this pin is an input receiving serial ST-BUS stream 15 at a data rate of $2.048 \mathrm{Mbit} / \mathrm{s}$. If Stream Pair Selection capability is enabled (see switching configuration section), this pin is the ST-BUS stream 9 output. When non-multiplexed bus structure is used, this pin should be left open. |
| - | 40 | 34 | $\begin{aligned} & \hline \text { STi14/ } \\ & \text { STo8 } \end{aligned}$ | ST-BUS Input 14 / ST-BUS Output 8 (Input/three-state output). This pin is only used if multiplexed CPU bus is selected. If 16 -input x 8 -output switching configuration is enabled in the SCB bits (IMS register), this pin is an input that receives serial ST-BUS stream 14 at a data rate of $2.048 \mathrm{Mbit} / \mathrm{s}$. If Stream Pair Selection capability is enabled (see switching configuration section), this pin is the ST-BUS stream 8 output. When non-multiplexed bus structure is used, this pin should be left open. |

## Device Overview

With the integration of voice, video and data services in the same network, there has been an increasing demand for systems which ensure that data at $\mathrm{N} \times 64 \mathrm{kbit} / \mathrm{s}$ rates maintain sequence integrity while being transported through time-slot interchange circuits. This requirement demands time-slot interchange devices which perform switching with constant throughput delay for wideband data applications while guaranteeing minimum delay for voice channels.

The MT8986 device meets the above requirement and allows existing systems based on the MT8980D to be easily upgraded to maintain the data integrity when wideband data is transported. The device is designed to switch 32,64 or $\mathrm{N} \times 64 \mathrm{kbit} / \mathrm{s}$ data. The MT8986 can provide frame integrity for data applications and minimum throughput switching delay for voice applications on a per channel basis.

The serial streams of the MT8986 device can operate at 2.048 , 4.096 or $8.192 \mathrm{Mbit} / \mathrm{s}$ and are arranged in $125 \mu \mathrm{~s}$ wide frames which contain 32,64 and 128 channels, respectively. In addition, a built-in rate conversion circuit allows the user to interconnect various backplane speeds like 2.048 or 4.096 or $8.192 \mathrm{Mb} / \mathrm{s}$ while maintaining the control of throughput delay function on a per-channel basis.

By using Zarlink Message mode capability, the microprocessor can access input and output time-slots on a per channel basis to control external circuits or other ST-BUS devices. The MT8986 automatically identifies the polarity
of the frame synchronization input signal and configures its serial port to be compatible to both ST-BUS and GCI formats.

In the 44 pin packages, two different microprocessor bus interfaces can be selected through an input mode pin (IM): Non-Multiplexed or Multiplexed. These interfaces provide compatibility with Intel/National multiplexed and Motorola Multiplexed/Non-Multiplexed buses. In 44 pin, the MT8986 provides a $16 \times 8$ switching configuration to form a $512 \times 256$ channel blocking matrix. Also, a flexible Stream Pair Selection operation allows the software selection of which pair of input and output streams can be connected to an internal $128 \times 128$ matrix. See Switching Configurations section for details.

## Functional Description

A functional Block Diagram of the MT8986 device is shown in Figure 1. Depending on the application, the MT8986 device receives TDM serial data at different rates and from different number of serial streams.

## Data and Connect Memories

For all data rates, the received serial data is converted to parallel format by the serial to parallel converters and stored sequentially in a Data Memory. Depending on the selected operation programmed in the IMS (Interface Mode Select) register, the Data Memory may have up to 512 bytes in use. The sequential addressing of the Data Memory is performed by an internal counter which is reset by the input 8 kHz frame pulse (FR) marking the frame boundaries of the incoming serial data streams.

Data to be output on the serial streams may come from two sources: Data Memory or Connect Memory. Locations in the Connect Memory, which is split into HIGH and LOW parts, are associated with particular ST-BUS output streams. When a channel is due to be transmitted on an ST-BUS output, the data for the channel can either be switched from an ST-BUS input as in connection mode or it can be from the Connect Memory Low as in message mode. Data destined for a particular channel on the serial output stream is read from the Data Memory or Connect Memory Low during the previous channel time-slot. This allows enough time for memory access and parallel to serial conversion.

## Connection and Message Modes

In connection mode, the addresses of the input source data for all output channels are stored in the Connect memories High (CMH) and Low (CML). The CML and CMH are mapped so that each location corresponds to an output channel on the output streams. The number of source address bits in CMH and CML to be utilized varies according to the switching configuration selected in the IMS register. For details on the use of the source address data (CAB and SAB bits), see CMH and CML bit descrip-tion (Figures $5 \& 6$ ). Once the source address bits are programmed by the CPU, the contents of the Data Memory at the selected address are transferred to the parallel-to-serial converters. By having the output channel specify the source channel through the connect memory, the user can route the same input channel to several output channels, allowing broadcast facility within the switch.

In message mode the CPU writes data to the Connect Memory Low locations corresponding to the output link and channel number. The contents of the Connect Memory Low are transferred directly to the parallel-to-serial converter one channel before it is to be output. The Connect Memory Low data is transmitted on to the output every frame until it is changed by the CPU with a new data.

The features of each output channel in the MT8986 are controlled by the Connect Memory High bits. These bits determine individual output channels to be in message or connection mode, select throughput delay types and enable/disable output drivers. The Connect Memory High also provides additional stream and channel address bits for some configurations. In addition, the Connect Memory High provides one bit to allow the user to control the CSTo output in $2.048 \mathrm{Mb} / \mathrm{s}$ applications.

If an output channel is set to high-impedance, the TDM serial stream output will be placed in high impedance during that channel time. In addition to the per-channel control, all channels on the TDM outputs can be placed in high impedance by pulling the ODE input pin LOW. This overrides the individual per-channel programming by the Connect Memory High bits.

The Connect Memory data is received via the Microprocessor Interface through the data I/O lines. The addressing of the MT8986 internal registers, Data and Connect memories is performed through address input pins and some bits of the device's Control register. The higher order address bits come from the Control register, which may be written or read through the microprocessor interface. The lower order address bits come directly from address input pins. For details on the device addressing, see Software Control and Control register bits description (Figure 3 \& Tables 5, 6 and 7).

## Serial Data Interface

The master clock (CLK) can be either at 4.096 or 8.192 MHz allowing serial data link operations at 2.048, 4.096 and $8.192 \mathrm{Mb} / \mathrm{s}$. These data rates can be independently selected on input and output streams allowing the MT8986 device to be used in various speed backplanes and in rate conversion applications. The selected data rates apply to the inputs or the output streams. Different bit rates among input streams or among output streams are not allowed. Due to the I/O data rate selection flexibility, two major operations can be selected: Identical or Different I/O data rates.

The DMO bit (Device Main Operation) in the IMS register is used for selecting between Identical I/O rates or Different I/O rates. On system power-up, the CPU should set up the DMO, the IDR (Input Data Rate) and ODR (Output Data Rate) bits located in the IMS register. When Identical I/O data rates are selected by the DMO bit, the switching configuration and the number of the device's input and output streams can be selected through the SCB bits (Switching Configuration Bits) in the IMS register. See Switching Configurations section for details.

Depending on the application, the interface clock can be selected to be twice the data rate or equal to the data rate. This selection is performed through bit CLKM in the IMS register. For applications where both serial inputs and outputs are at $2.048 \mathrm{Mb} / \mathrm{s}$ (ST-BUS or GCI format), the CLKM bit should be set LOW enabling the interface clock to be twice the bit rate. In applications where both inputs and outputs are at 4.096 or $8.192 \mathrm{Mb} / \mathrm{s}$, CLKM should be set HIGH enabling the interface clock to be equal to the bit rate. In applications where inputs and outputs are at different rates, the CLKM bit has no effect.

In applications with serial links at $2.048 \mathrm{Mb} / \mathrm{s}$ (see Figures 16 to 19), the input 8 kHz frame pulse can be in either ST-BUS or GCI format. The MT8986 device automatically detects the presence of an input frame pulse and identifies what type of backplane is present on the serial interface. Upon determining the interface connected to the serial port, the internal timing unit establishes the appropriate transmit and sampling edges. In ST-BUS format, every second falling edge of the 4.096 MHz clock marks a bit boundary and the input data is clocked in by the rising edge, three quarters of the way into the bit cell. In GCI format, every second rising edge of the 4.096 MHz clock marks the bit boundary while data sampling is performed during the falling edge, at three quarters of the bit boundaries.

For identical I/O rates at 4.096 and $8.192 \mathrm{Mb} / \mathrm{s}$ (see Figure 20), the clock and interface data rates are equal. The bit transmit and sampling edges vary according to the applied frame pulse polarity. For example, if the FR pulse polarity is positive, the bit transmit operation is done on every rising edge of CLK and the bit sampling on every falling edge. If the FR pulse polarity is negative, these edges are inverted. For different I/O rates, the MT8986 side operating at $2.048 \mathrm{Mb} / \mathrm{s}$ data rate will comply with ST-BUS or GCI interfaces for transmit and sampling procedures. The MT8986 side operating at 4.096 or $8.192 \mathrm{Mb} / \mathrm{s}$ behaves according to the frame pulse polarity applied. See Figures 22 to 25 .

## Switching Configurations

Switching configurations are determined basically by the interface rates selected at the serial inputs and outputs. To specify the switching configuration required, the IMS register has to be initialized on system power-up. In case of Identical I/O rates (DMO bit LOW) at both inputs and outputs, the switching configuration is selected by the two SCB bits as shown in Table 8 (see IMS register). In case of different I/O rates (DMO bit HIGH), the switching configuration is always non-blocking with different number of I/O streams which is defined by the IDR and ODR bits (see IMS register).

## Identical Input/Output Data Rates

When identical input/output data rate is selected by the DMO bit, the I/O rate is determined by the IDRO-1 bits, and the ODRO-1 bits are ignored. For each data rate specified by the IDR bits, different switching configurations can be selected in the SCB1-0 bits.

## Serial Links with Data Rates at 2.048 Mb/s

When $2.048 \mathrm{Mb} / \mathrm{s}$ data rate is selected at the IDR bits, four different I/O configurations can be selected by the SCB1-0 bits (see Table 8); $8 \times 8,16 \times 8,4 \times 4$ with stream pair selection and nibble switching.

If $8 \times 8$ switching configuration is selected, a $256 \times 256$ channel non-blocking switching matrix is available. In this configuration, the MT8986 device is configured with 8 input and 8 output data streams with $3264 \mathrm{Kbit} / \mathrm{s}$ channels each. The interface clock for this operation is 4.096 MHz with both ST-BUS and GCI compatibilities and the perchannel selection between variable and constant throughput delay functions is provided. This configuration is available in both the 40 and 44 pin packages.

In $16 \times 8$ switching configuration, a $512 \times 256$ channel blocking switch matrix is available. This configuration is only provided in the 44 pin package and when the CPU interface is configured in multiplexed bus mode. The device clock in this application is 4.096 MHz , ST-BUS or GCI compatible. This configuration only provides variable throughput delay.

If the stream pair selection switching configuration is selected, only four input and four outputs ( 4 pairs of serial streams) can be selected by the CPU to be internally connected to the switch matrix, totalling a $128 \times 128$ channel non-blocking switch. From the 10 serial link pairs available, two pairs are permanently connected to the internal matrix (STi0/STo0 and STi1/STo1). An internal stream pair selection capability allows two additional pairs of serial links to be selected from the remaining 8 pairs (from STi/STo2 to STi9/STo9) and be connected to the internal matrix along with the permanently connected STi0/STo0 and STi1/STo1 streams. The two additional pair of streams called stream pair A and stream pair B, should be selected in the Stream Pair Selection register (SPS). The device clock for this operation is 4.096 MHz compatible to ST-BUS and GCI interfaces. In addition, the per-channel selection between variable or constant throughput delay is available. This configuration is only provided in the 44 pin packages.

In case of nibble switching, 4-bit wide $32 \mathrm{~kb} / \mathrm{s}$ data channels can be switched within the device. In this case, every serial stream is run at $2.048 \mathrm{Mb} / \mathrm{s}$ and transports 64 nibbles per frame. When Nibble Switching is selected at SCB bits, the MT8986 automatically assumes a 8 input x 4 output stream configuration, providing a blocking switch matrix of $512 \times 256$ nibbles. If a non-blocking switch matrix is required for nibble switching, the switch capacity is reduced to $256 \times 256$ channel with a 4 input x 4 output configuration; the non-blocking matrix can be arranged by the user by selecting any four of the 8 input streams. In nibble switching the interface clock is 4.096 MHz .

## Serial Links with Data Rates at 4.096 Mb/s

Two I/O configurations can be enabled by the SCB bits when input and output data rates are $4.096 \mathrm{Mb} / \mathrm{s}$ on each serial stream: $8 \times 4$ and $4 \times 4$. When $8 \times 4$ switching configuration is selected, a $512 \times 256$ channel blocking switch is available with serial streams carrying $64,64 \mathrm{~Kb} / \mathrm{s}$ channels each. For this operation, a 4.096 MHz interface clock equal to the bit rate should be provided to MT8986. Only variable throughput delay mode is provided.

In case of $4 \times 4$ switching configuration, a $256 \times 256$ channel non-blocking switch is available with serial streams carrying $64,64 \mathrm{~Kb} / \mathrm{s}$ channels each. In this configuration, the interface clock is 4.096 MHz and the per-channel selection between variable and constant throughput delay operation is provided. Figure 20 shows the timing for $4.096 \mathrm{Mb} / \mathrm{s}$ operation.

## Serial Links with Data Rates at 8.192 Mb/s

Only 2 input $\times 2$ output stream configuration is available for $8.192 \mathrm{Mb} / \mathrm{s}$, allowing a $256 \times 256$ channel non-blocking switch matrix to be implemented. To enable this operation, the IDR bits should be programmed to select $8.192 \mathrm{Mb} / \mathrm{s}$ rates and the SCB bits have no effect. At $8.192 \mathrm{Mb} / \mathrm{s}$, every input and output stream provides 128 time-slots per
frame. The interface clock for this operation should be 8.192 MHz . Figure 20 shows the timing for $8.192 \mathrm{Mb} / \mathrm{s}$ operation.

Table 1 summarizes the MT8986 switching configurations for identical I/O data rates.

| Serial <br> Interface <br> Data Rate | Interface <br> Clock <br> required at <br> CLK Pin <br> (MHz) | Number of <br> Input x <br> Output <br> Streams | Matrix <br> Channel <br> Capacity | Input/Output <br> Streams Used | Variable/ <br> Constant <br> throughput <br> Delay <br> Selection |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $2 \mathrm{Mb} / \mathrm{s}$ | 4.096 | $8 \times 8$ | $256 \times 256$ Non-Blocking | STi0-7/STo0-7 | Yes |
| $2 \mathrm{Mb} / \mathrm{s}$ <br> $*$ | 4.096 | $16 \times 8$ <br> $*$ | $512 \times 256$ Blocking | STi0-15/STo0-7 | No |
| $2 \mathrm{Mb} / \mathrm{s}$ <br> $*$ | 4.096 | $10 \times 10$ <br> $*$ | $128 \times 128$ Non-Blocking <br> (only 4 input $\times 4-$-output <br> can be selected) | STi0-9/STo0-9 | Yes |
| Nibble <br> Switching <br> $(2 \mathrm{Mb} / \mathrm{s})$ | 4.096 | $8 \times 4$ | $512 \times 256$ Nibbles | STi0-7/STo0-3 | No |
| $4 \mathrm{Mb} / \mathrm{s}$ | 4.096 | $8 \times 4$ | $512 \times 256$ Blocking | STi0-7/STo0-3 | No |
| $4 \mathrm{Mb} / \mathrm{s}$ | 4.096 | $4 \times 4$ | $256 \times 256$ Non-Blocking | STi0-3/STo0-3 | Yes |
| $8 \mathrm{Mb} / \mathrm{s}$ | 8.192 | $2 \times 2$ | $256 \times 256$ Non-Blocking | STi0-1/STo0-1 | Yes |

Table 1 - Switching Configurations for Identical Input and Output Data Rates

*     - only in the 44 pin packages


## Different Input/Output Data Rates

When Different I/O rate is selected by the DMO bit, the input and output data rates should be selected at the IDR and ODR bits, respectively. The Switching Configuration Bits (SCB) are ignored with this operation. This selection allows the user to multiplex conventional $2.048 \mathrm{Mb} / \mathrm{s}$ serial streams into two higher rates and vice-versa. In addition to the rate conversion itself, the MT8986 allows for a complete $256 \times 256$ channel non-blocking switch at different rates. In this operation, the per-channel variable/constant throughput delay selection is provided.

Depending on which data rates are programmed for input and output streams, the number of data streams used on the input and output as well as the serial interface clock (CLK input pin) is different. Once the CPU defines the data rates at the IDR and ODR bits, the MT8986 automatically configures itself with the appropriate number of input and output streams for the desired operation. Table 2 summarizes the four options available when MT8986 is used with different I/O rates. Figures 22 to 25 show the timing for each of the four modes shown in Table 2.

| Input and Output <br> Data Rates | Interface <br> Clock <br> required at <br> CLK Pin <br> (MHz) | Number <br> of Input <br> (Output <br> Streams | Matrix <br> Channel Capacity | Input/Output <br> Streams Used | Cariable/ <br> Constant <br> throughput <br> Delay Selection |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $2 \mathrm{Mb} / \mathrm{sto} 4 \mathrm{Mb} / \mathrm{s}$ | 4.096 | $8 \times 4$ | $256 \times 256$ Non-Blocking | STi0-7/STo0-3 | Yes |
| $2 \mathrm{Mb} / \mathrm{s}$ to $8 \mathrm{Mb} / \mathrm{s}$ | 8.192 | $8 \times 2$ | $256 \times 256$ Non-Blocking | STi-7/STo-0-1 | Yes |
| $4 \mathrm{Mb} / \mathrm{s}$ to $2 \mathrm{Mb} / \mathrm{s}$ | 4.096 | $4 \times 8$ | $256 \times 256$ Non-Blocking | STi0-3/STo-7 | Yes |
| $8 \mathrm{Mb} / \mathrm{s}$ to $2 \mathrm{Mb} / \mathrm{s}$ | 8.192 | $2 \times 8$ | $256 \times 256$ Non-Blocking | STi0-1/STo0-7 | Yes |

Table 2-Switching Configurations for Different I/O Data Rates

## Input Frame Offset Selection

When 4.096 or $8.192 \mathrm{Mb} / \mathrm{s}$ serial interfaces are selected, the MT8986 device provides a feature called Input Frame Offset allowing the user to compensate for the varying delays at the incoming serial inputs while building large
switch matrices. Usually, different delays occur on the digital backplanes causing the data and frame synchronization signals to be skewed at the input of the switch device. This may result in the system frame synchronization pulse to be active at the MT8986 FR input before the first bit of the frame is received at the serial inputs.

When the input frame offset is enabled, an "internal delay" of up to four clock periods is added to the actual data input sampling, providing the MT8986 serial timing unit a new input frame reference. An internal virtual frame is created which is aligned with the framing of the actual serial data coming in at the serial inputs and not with the FR frame pulse input. In this operation, the transmission of the output frame on the serial links is still aligned to the frame pulse input signal (FR).

The selection of the data input sampling delay is defined by the CPU in the Frame Input Offset Register (FIO). If this function is not required in the user's applications, the FIO register should be set up during system initialization to a state where offset functions are disabled.

## Delay Through the MT8986

The switching of information from the input serial streams to the output serial streams results in a delay. Depending on the type of information to be switched, the MT8986 device can be programmed to perform time-slot interchange functions with different throughput delay capabilities on a per-channel basis. For voice applications, variable throughput delay can be selected ensuring minimum delay between input and output data. In wideband data applications, constant throughput delay can be selected maintaining the frame integrity of the information through the switch.

The delay through the MT8986 device varies according to the type of throughput delay selected in the $\overline{\mathrm{V}} / \mathrm{C}$ bit of the connect memory high.

## Variable Throughput Delay Mode ( $\overline{\mathrm{V}} / \mathrm{C}$ bit $=0$ )

## Identical I/O Data Rates

The delay in this mode is dependent on the combination of source and destination channels and it is independent of the input and output streams. The minimum delay achievable in the MT8986 depends on the data rate selected for the serial streams. For instance, for $2.048 \mathrm{Mb} / \mathrm{s}$ the minimum delay achieved corresponds to three time-slots. For $4.096 \mathrm{Mb} / \mathrm{s}$ it corresponds to five time-slots while for $8.192 \mathrm{Mb} / \mathrm{s}$ it is nine time-slots. Switching configurations with input and output channels that provides more than its corresponding minimum throughput delay, will have a throughput delay equal to the difference between the output and input channels; i.e., the throughput delay will be less than one frame period. Table 3a shows the MT8986 throughput delay for each data rate operation.

| Input Rate | Output Channel (\# m) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{m}<\mathbf{n}$ | $\mathrm{m}=\mathrm{n}, \mathrm{n}+1, \mathrm{n}+2$ | $\mathrm{m}=\mathrm{n}+3, \mathrm{n}+4$ | $\mathbf{m}=\mathrm{n}+5, \ldots \mathrm{n}+8$ | $\mathbf{m}>\mathbf{n}+\mathbf{8}$ |
| $2.048 \mathrm{Mb} / \mathrm{s}$ | 32-(n-m) t.s. | $\mathrm{m}-\mathrm{n}+32 \mathrm{t} . \mathrm{s}$. | m-n t.s. | m-n t.s. | m-n t.s. |
| $4.096 \mathrm{Mb} / \mathrm{s}$ | 64-(n-m) t.s. | $m-n+64$ t.s. | $\mathrm{m}-\mathrm{n}+64$ t.s. | $\mathrm{m}-\mathrm{n}$ t.s. | m-n t.s. |
| $8.192 \mathrm{Mb} / \mathrm{s}$ | 128-(n-m) t.s. | m-n+128 t.s. | $\mathrm{m}-\mathrm{n}+128$ t.s. | $\mathrm{m}-\mathrm{n}+128$ t.s. | m-n t.s. |

Table 3a - Variable Throughput Delay Values for Identical I/O Rate Applications
$\mathrm{n}=$ input channel, t.s. = time-slot

## Different I/O Data Rates

Except for $2 \mathrm{Mb} / \mathrm{s}$ to $4 \mathrm{Mb} / \mathrm{s}$ and $2 \mathrm{Mb} / \mathrm{s}$ to $8 \mathrm{Mb} / \mathrm{s}$ rate conversion operations, the throughput delay in the MT8986 may vary according to the output stream used for switching.

Table 3b explains the worst case conditions for the throughput delay when different I/O data rate switching configurations are used.

| I/O Data Rate Configuration | Output Stream Used |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 0, 1 | 2, 3 | 4, 5 | 6, 7 |
| $2 \mathrm{Mb} / \mathrm{s}$ to $4 \mathrm{Mb} / \mathrm{s}$ | $\begin{aligned} & \text { dmin }=5 \mathrm{x} 4 \mathrm{Mb} / \mathrm{s} \text { t.s. } \\ & \mathrm{dmax}=1 \mathrm{fr} .+(4 \mathrm{x} 4 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \end{aligned}$ |  |  |  |
| $2 \mathrm{Mb} / \mathrm{s}$ to $8 \mathrm{Mb} / \mathrm{s}$ | $\begin{aligned} & \text { dmin }=9 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \mathrm{t.s.} \\ & \mathrm{dmax}=1 \mathrm{fr} .+(8 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \quad \text { t.s. }) \end{aligned}$ |  |  |  |
| $4 \mathrm{Mb} / \mathrm{s}$ to $2 \mathrm{Mb} / \mathrm{s}$ | $\begin{aligned} & \text { dmin }=3 \times 2 \mathrm{Mb} / \mathrm{s} \text { t.s. } \\ & \mathrm{dmax}=1 \mathrm{fr} .+(2 \times 2 \mathrm{Mb} / \mathrm{s} \quad \text { t.s. }) \end{aligned}$ |  | $\begin{aligned} & \text { dmin }=(2 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \text { t.s. })+(1 \mathrm{x} 4 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \\ & \mathrm{dmax}=1 \mathrm{fr} .+(1 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \text { t.s. })+(1 \mathrm{x} 4 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \end{aligned}$ |  |
| $8 \mathrm{Mb} / \mathrm{s}$ to $2 \mathrm{Mb} / \mathrm{s}$ | $\begin{array}{r} \mathrm{dmin}=3 \times 2 \mathrm{Mb} / \mathrm{s} \mathrm{t.s.} \\ \mathrm{dmax}=1 \mathrm{fr} .+(2 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \\ \text { t.s. }) \end{array}$ | $\begin{gathered} \text { dmin }=(2 \times 2 \mathrm{Mb} / \mathrm{s} \text { t.s. })^{+} \\ (3 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \\ \text { dmax }=1 \mathrm{fr} .+(1 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \\ \text { t.s. })+(3 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \end{gathered}$ | $\begin{gathered} \mathrm{dmin}=(2 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \text { t.s. })^{+} \\ (2 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \mathrm{t.s.}) \\ \mathrm{dmax}=1 \mathrm{fr} .+(1 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \\ \text { t.s. })+(2 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \end{gathered}$ | $\begin{gathered} \text { dmin }=(2 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \text { t.s. })+ \\ (1 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \\ \mathrm{dmax}=1 \mathrm{fr} .+(1 \mathrm{x} 2 \mathrm{Mb} / \mathrm{s} \\ \text { t.s. })+(1 \mathrm{x} 8 \mathrm{Mb} / \mathrm{s} \text { t.s. }) \end{gathered}$ |

## Table 3b - Min/Max Throughput Delay Values for Different I/O Rate Applications

Notes: dmin and dmax are measured in time-slots and at the point in time when the output channel is completely shifted out.

$$
\text { t.s. }=\text { time-slot }
$$

fr. $=125 \mu$ s frame
$2 \mathrm{Mb} / \mathrm{s}$ t.s. $=3.9 \mu \mathrm{~s}$
$4 \mathrm{Mb} / \mathrm{s}$ t.s. $=1.95 \mu \mathrm{~s}$
$8 \mathrm{Mb} / \mathrm{s}$ t.s. $=0.975 \mu \mathrm{~s}$

## Constant Throughput Delay mode ( $\overline{\mathrm{V}} / \mathrm{C}$ bit $=1$ )

In this mode frame sequence integrity is maintained in both Identical and Different I/O Data Rate operations by making use of a multiple Data-Memory buffer technique. The input channels written in any of the buffers during frame N will be read out during frame $\mathrm{N}+2$. In applications at $2.048 \mathrm{Mb} / \mathrm{s}$ for instance, the minimum throughput delay achievable in constant delay mode will be 32 time-slots; for example, when input time-slot 32 (channel 31) is switched to output time-slot 1 (channel 0 ). Likewise, the maximum delay is achieved when the first time slot in a frame (channel 0 ) is switched to the last time-slot in the frame (channel 31), resulting in 94 time-slots of delay.

To summarize, any input time-slot from input frame N will always be switched to the destination time-slot on output frame N+2. Table 4 describes the MT8986 constant throughput delay values for different data rates.

| Data Rate | Throughput Delay (d) |
| :---: | :---: |
| $2.048 \mathrm{Mb} / \mathrm{s}$ | ```\(\mathrm{d}=[32+(32-\mathrm{IN})+(\) OUT -1\()]\); (expressed in \# time-slots) \(2.048 \mathrm{Mb} / \mathrm{s}\) time-slot: \(3.9 \mu \mathrm{~s}\) IN: input time-slot (from 1 to 32 ) OUT: output time-slot (from 1 to 32)``` |
| $4.096 \mathrm{Mb} / \mathrm{s}$ | ```\(\mathrm{d}=[64+(64-\mathrm{IN})+(\mathrm{OUT}-1)]\); (expressed in \# time-slots) \(4.096 \mathrm{Mb} / \mathrm{s}\) time-slot: \(1.95 \mu \mathrm{~s}\) IN: input time-slot (from 1 to 64) OUT: output time-slot (from 1 to 64)``` |
| $8.192 \mathrm{Mb} / \mathrm{s}$ | ```d=[128 + (128 - IN) + (OUT - 1)]; (expressed in # time-slots) 8.192 Mb/s time-slot: 0.975 \mus IN: input time-slot (from 1 to 128) OUT: output time-slot (from 1 to 128)``` |

Table 4-Constant Throughput Delay values

## Microprocessor Port

The non-multiplexed bus interface provided by the MT8986 device is identical to that provided in MT8980 Digital Switch device. In addition to the non-multiplexed bus, the MT8986 device provides an enhanced microprocessor interface with multiplexed bus structure compatible to both Motorola and Intel buses. The multiplexed bus structure is available only in the 44 pin packages and it is selected by the CPU Interface Mode (IM) input pin.

If IM input pin is not connected (left open) or grounded, the MT8986 parallel port assumes its default Motorola nonmultiplexed bus mode identical to that of MT8980. If IM input is connected HIGH, the internal parallel microport provides compatibility to MOTEL interface allowing direct connection to Intel, National and Motorola CPUs.

The MOTEL circuit (MOtorola and InTEL compatible bus) automatically identifies the type of CPU Bus connected to the MT8986 device. This circuit uses the level of the DS/RD input pin at the rising edge of the AS/ALE to identify the appropriate bus timing connected to the MT8986. If DS/RD is LOW at the rising edge of AS/ALE then Motorola bus timing is selected. If $D S / \overline{R D}$ is HIGH at the rising edge of AS/ALE, then Intel bus timing is selected.

When MT8986 parallel port is operating in Motorola, National or Intel multiplexed bus interfaces, the signals available for controlling the device are: ADO-AD7 (Data and Address), ALE/AS (Address Latch Enable/Address Strobe), DS/RD (Data Strobe/Read), R/WMWR (Read/WritelWrite), $\overline{C S}$ (Chip Select) and DTA (Data Acknowledgement). In Motorola non-multiplexed bus, the interface control signals are: data bus (AD0-AD7), six address input lines (A0-A5) and four control lines ( $\overline{C S}, D S, R / \bar{W}$ and $\overline{D T A}$ ). See Figures 26 to 28 for each CPU interface timing.

The MT8986 parallel microport provides the access to the IMS, Control registers, the Connection Memory High, the Connection Memory Low and the Data Memory. All locations can be read or written except for the data memory which can be read only.

## Software Control

The address bus on the microprocessor interface selects the internal registers and memories of the MT8986. If the A5 address input is LOW, then the MT8986 Internal Control, Interface Mode, Stream Pair Selection and Frame Input Offset registers are addressed by the A4 to A0 bits according to Table 5. If A5 input is HIGH, then the remaining address input lines are used to select memory subsections of up to 128 locations corresponding to the maximum number of channels per input or output stream. The address input lines and the Stream Address bits (STA) of the Control register give the user the capability of accessing all sections of the MT8986 Data and Connect memories.

The Control and Interface Mode Selection registers together control all the major functions of the device. The Interface Mode Select register should be set up during system power-up to establish the desired switching configuration as explained in the Serial Interface and Switching Configurations sections.

The Control register is dynamically used by the CPU to control switching operations in the MT8986. The Control register selects the device's internal memories and its subsections to specify the input and output channels selected for switching procedures.

The data in the Control register consists of Split memory and Message mode bits, Memory select and Stream Address bits. The memory select bits allow the Connect Memory HIGH or LOW or the Data Memory to be chosen, and the Stream Address bits define an internal memory subsections corresponding to input or output ST-BUS streams.

| A7 | A6 | A5 | A4 | A3 | A2 | A1 | A0 | Location |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| X | X | 0 | 0 | 0 | 0 | 0 | 0 | Control Register |
| X | X | 0 | 0 | 0 | 0 | 0 | 1 | Interface Mode Select Register |
| X | X | 0 | 0 | 0 | 0 | 1 | 0 | Stream Pair Select Register |
| X | X | 0 | 0 | 0 | 0 | 1 | 1 | Frame Input Offset Register |
| 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | Channel 0* |
| $\begin{aligned} & \hline 0 \\ & \bullet \\ & \bullet \\ & 0 \end{aligned}$ | $\begin{aligned} & \hline 0 \\ & \stackrel{\rightharpoonup}{\bullet} \\ & \hline \end{aligned}$ | $\begin{aligned} & 1 \\ & 1 \\ & 1 \\ & 1 \end{aligned}$ | $\begin{aligned} & \hline 0 \\ & \stackrel{\rightharpoonup}{\bullet} \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 0 \\ & \bullet \\ & \bullet \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 0 \\ & \bullet \\ & \bullet \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline 0 \\ & \stackrel{\bullet}{\bullet} \\ & \hline \end{aligned}$ | $\begin{aligned} & 1 \\ & \bullet \\ & \bullet \\ & \hline \end{aligned}$ | $\begin{gathered} \text { Channel 1* } \\ \text { • } \\ \text { • } \\ \text { Channel 31* } \end{gathered}$ |
| 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | Channel 32** |
| $0$ | 1 $\bullet$ $\bullet$ 1 | $\begin{aligned} & 1 \\ & 1 \\ & 1 \\ & 1 \end{aligned}$ | $0$ | 0 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | 1 $\bullet$ $\bullet$ 1 | $\begin{gathered} \text { Channel } 33^{* *} \\ \text { • } \\ \text { Channel } 63^{* *} \end{gathered}$ |
| 1 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | 1 1 1 1 | 0 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | 0 $\bullet$ $\bullet$ 1 | Channel 64*** - Channel $127^{* * *}$ |

Table 5 - Address Memory Map
*: channels 0 to 31 are used in $2.048 \mathrm{Mb} / \mathrm{s}(8 \times 8,16 \times 8$ and $10 \times 10)$
$*^{*}$ : channels 0 to 63 are used in $4.096 \mathrm{Mb} / \mathrm{s}$ (Nibble Switching, $4 \times 4,8 \times 4$ or Different I/O rates)
***: channels 0 to 127 are used in $8.192 \mathrm{Mb} / \mathrm{s}(2 \times 2$ or Different I/O rates)

Bit 7 (Slip Memory) of the Control register allows split memory operation whereby reads are from the Data memory and writes are to the Connect Memory LOW.

The Message Enable bit (bit 6) places every output channel on every output stream in message mode; i.e., the contents of the Connect Memory LOW (CML) are output on the ST-BUS output streams once every frame unless the ODE input pin is LOW. If ME bit is HIGH, then the MT8986 behaves as if bits 2 (Message Channel) and 0 (Output Enable) of every Connect Memory HIGH (CMH) locations were set to HIGH, regardless of the actual value. If ME bit is LOW, then bit 2 and 0 of each Connect Memory HIGH location function normally. In this case, if bit 2 of the CMH is HIGH, the associated ST-BUS output channel is in Message mode. If bit 2 of the CMH is LOW, then the contents of the SAB and CAB bits of the CMH and CML define the source information (stream and channel) of the time-slot that is to be switched to an output.

If the ODE input pin is LOW, then all serial outputs are high-impedance. If ODE is HIGH, then bit 0 (Output Enable) of the CMH location enables (if HIGH) or disables (if LOW) the output drivers for the corresponding individual STBUS output stream and channel.

The contents of bit 1 (CSTo) of each Connection Memory High location is output on CSTo pin once every frame. The CSTo pin is a 2048 Mbit/s output which carries 256 bits. If CSTo bit is set HIGH, the corresponding bit on CSTo output is transmitted HIGH. If CSTo bit is LOW, the corresponding bit on the CSTo output is transmitted LOW. The contents of the 256 CSTo bits of the CMH are transmitted sequentially on to the CSTo output pin and are synchronous to the $2.048 \mathrm{Mb} / \mathrm{s}$ ST-BUS streams. To allow for delay in any external control circuitry the contents of the CSTo bit is output one channel before the corresponding channel on the ST-BUS streams. For example, the contents of CSTo bit in position $0(S T 0, \mathrm{CHO})$ of the CMH, is transmitted synchronously with ST-BUS channel 31, bit 7. The contents of CSTo bit in position 32 (ST1, CHO) of the CMH is transmitted during ST-BUS channel 31 bit 6. For more detailed description of the CSTo operation, see section 6 of Application Note MSAN-123.
The Bit $\overline{\mathrm{V}} / \mathrm{C}$ (Variable/Constant Delay) of each Connect Memory High location allows the per-channel selection between Variable and Constant throughput delay modes.

## Initialization of the MT8986

On initialization or power up, the contents of the Connection Memory High can be in any state. This is a potentially hazardous condition when multiple MT8986 ST-BUS outputs are tied together to form matrices, as these outputs may conflict. The ODE pin should be held low on power up to keep all outputs in the high impedance condition.

During the microprocessor initialization routine, the microprocessor should program the desired active paths through the matrices, and put all other channels into the high impedance state. Care should be taken that no two ST-BUS outputs drive the bus simultaneously. When this process is complete, the microprocessor controlling the matrices can bring the ODE signal high to relinquish high impedance state control to the $\mathrm{CMH}_{\mathrm{b}} \mathrm{Os}$.

Control Register - Read/Write


Figure 3 - Control Register Description

| Identical <br> I/O <br> Rate | \# of Input x <br> Output <br> Streams | STA bits used to <br> select subsections of <br> the Data <br> Memory | STA bits used to <br> select subsections of <br> the Connection <br> Memory | Input Address pins used to <br> select individual Connection <br> and Data Memory positions <br> within the selected subsection |
| :---: | :---: | :--- | :--- | :--- |
| $2 \mathrm{Mb} / \mathrm{s}$ | 8 x 8 | STA2, STA1, STA 0 | STA2, STA1, STA0 | A4, A3, A2, A1, A0 |
| $2 \mathrm{Mb} / \mathrm{s} *$ | $4 \times 4 *$ | STA1, STA 0 | STA1, STA 0 | A4, A3, A2, A1, A0 |


| Identical <br> I/O <br> Rate | \# of Input x <br> Output <br> Streams | STA bits used to <br> select subsections of <br> the Data <br> Memory | STA bits used to <br> select subsections of <br> the Connection <br> Memory | Input Address pins used to <br> select individual Connection <br> and Data Memory positions <br> within the selected subsection |
| :---: | :---: | :--- | :--- | :--- |
| $2 \mathrm{Mb} / \mathrm{s} *$ | $16 \mathrm{x} 8 *$ | STA3, STA2, STA1, <br> STA0 | STA2, STA1, STA0 | A4, A3, A2, A1, A0 |
| $4 \mathrm{Mb} / \mathrm{s}$ | $4 \times 4$ | STA1, STA0 | STA1, STA0 | $\mathrm{A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |
| $4 \mathrm{Mb} / \mathrm{s}$ | 8 x 4 | STA2, STA1, STA0 | STA1, STA0 | $\mathrm{A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |
| $8 \mathrm{Mb} / \mathrm{s}$ | $2 \times 2$ | STA0 | STA0 | $\mathrm{A} 7, \mathrm{~A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |
| Nibble Switch <br> $(2 \mathrm{Mb} / \mathrm{s})$ | $8 \times 4$ | STA2, STA1, STA0 | STA1, STA0 | $\mathrm{A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0 * *$ |

Table 6 - Use of STA Bits for Identical I/O Data Rate Operation

*     - only in the 44 pin packages.
** - for Data Memory Read operations A0 is not required since two nibbles are provided per read access.

| Different <br> I/O <br> Rate | Input x <br> Output <br> Streams <br> Config. | STA bits used to <br> select <br> Data <br> Memory <br> subsections | STA bits used to <br> select <br> Connection <br> Memory <br> subsections | Input Address pins used to <br> access individual Data <br> Memory <br> positions within the <br> selected subsection | Input Address pins used to <br> access individual <br> Connection Memory <br> positions within the <br> selected subsection |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $2 \mathrm{Mb} / \mathrm{s}$ to 4 <br> $\mathrm{Mb} / \mathrm{s}$ | 8 x 4 | STA2, STA1, <br> STA0 | STA1, STA0 | A4, A3, A2, A1, A0 | $\mathrm{A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |
| $2 \mathrm{Mb} / \mathrm{s}$ to 8 <br> $\mathrm{Mb} / \mathrm{s}$ | 8 x 2 | STA2, STA1, <br> STA0 | STA0 | $\mathrm{A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ | $\mathrm{~A} 7, \mathrm{~A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |
| $4 \mathrm{Mb} / \mathrm{s}$ to 2 <br> $\mathrm{Mb} / \mathrm{s}$ | 4 x 8 | STA1, STA0 | STA2, STA1, <br> STA0 | $\mathrm{A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ | $\mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |
| $8 \mathrm{Mb} / \mathrm{s}$ to 2 <br> $\mathrm{Mb} / \mathrm{s}$ | 2 x 8 | STA0 | STA2, STA1, <br> STA0 | $\mathrm{A} 7, \mathrm{~A} 6, \mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ | $\mathrm{~A} 4, \mathrm{~A} 3, \mathrm{~A} 2, \mathrm{~A} 1, \mathrm{~A} 0$ |

Table 7 - Use of STA Bits for Different I/O Data Rate Operation

Note: In rate conversion applications, Data Memory subsections have different sizes than Connection Memory subsections. This implies that different address inputs are used to select individual positions within the subsections for each type of memory.

## Interface Mode Selection Register - Read/Write



Figure 4 -IMS Register Description

| DMO Bit | Data Rate Selected at IDR bits (Mb/s) | SCB1 | SCB0 | Configuration |
| :---: | :---: | :---: | :---: | :---: |
| LOW <br> Identical <br> I/O <br> Rates | 2.048 | 0 | 0 | 8 inputs x 8 outputs - Non Blocking |
|  |  | 0 | 1 | 16 inputs x 8 outputs - Blocking** |
|  |  | 1 | 0 | Stream pair selection capability (internal channel capacity $=128 \times 128$ ) - <br> Non Blocking** |
|  |  | 1 | 1 | Nibble Switching - 8 inputs x 4 outputs - Blocking |
|  | 4.096 | 0 | 0 | 8 inputs x 4 outputs - Blocking |
|  |  | 0 | 1 | 4 inputs x 4 outputs - Non-Blocking |
|  |  | 1 | 0 | Reserved |
|  |  | 1 | 1 | Reserved |
|  | 8.192 | no <br> effect | no effect | 2 inputs x 2 outputs - Non-Blocking |
| HIGH <br> Different I/O <br> Rates | Input/Output Rate selected in IDR/ODR bits | $\begin{gathered} \text { no } \\ \text { effect } \end{gathered}$ | $\begin{gathered} \text { no } \\ \text { effect } \end{gathered}$ | Reserved |

Table 8 - Switching Configurations for Identical I/O Rates

[^0]
## Connection Memory High - Read/Write



Figure 5 - Connection Memory High (CMH) Bits

[^1]
## Connection Memory Low - Read/Write



Figure 6 - Connection Memory Low (CML) Bits

| Identical <br> I/O <br> Rate | \# of Input $x$ Output Streams | CAB bits used to determine the source channel for the connection | SAB bits used to determine the source stream for the connection |
| :---: | :---: | :---: | :---: |
| $2 \mathrm{Mb} / \mathrm{s}$ | 8x8 | CAB4 to CAB0 (32 channel/inp. stream) | SAB2, SAB1, SAB0 |
| $2 \mathrm{Mb} / \mathrm{s}$ * | $4 \times 4$ * | CAB4 to CAB0 (32 channel/inp. stream) | SAB2, SAB1 |
| $2 \mathrm{Mb} / \mathrm{s}$ * | 16x8* | CAB4 to CAB0 (32 channel/inp. stream) | SAB3, SAB2, SAB1, SAB0 |
| $4 \mathrm{Mb} / \mathrm{s}$ | $4 \times 4$ | CAB5 to CAB0 ( 64 channel/inp. stream) | SAB2, SAB1 |
| $4 \mathrm{Mb} / \mathrm{s}$ | 8 x 4 | CAB5 to CAB0 (64 channel/inp. stream) | SAB2, SAB1, SAB0 |
| $8 \mathrm{Mb} / \mathrm{s}$ | 2x2 | CAB6 to CAB0 (128 channel/inp. stream) | SAB2 |
| Nibble Switch ( $2 \mathrm{Mb} / \mathrm{s}$ ) | 8 x 4 | CAB5 to CAB0 (64 nibble/inp. stream) | SAB2, SAB1, SAB0 |

Table 9 - CAB and SAB Bits Programming for Identical I/O Rate Applications

[^2]| Different <br> I/O <br> Rate | \# of Input x <br> Output Streams | CAB bits used to determine the source <br> channel for the connection | SAB bits used to <br> determine the source <br> stream for the <br> connection |
| :--- | :---: | :--- | :--- |
| $2 \mathrm{Mb} / \mathrm{s}$ to $4 \mathrm{Mb} / \mathrm{s}$ | $8 \times 4$ | CAB4 to CAB0 $(32$ channel/inp. stream $)$ | $\mathrm{SAB} 2, \mathrm{SAB} 1, \mathrm{SAB} 0$ |
| $2 \mathrm{Mb} / \mathrm{s}$ to $8 \mathrm{Mb} / \mathrm{s}$ | $8 \times 2$ | CAB4 to CAB0 $(32$ channel/inp. stream $)$ | $\mathrm{SAB} 2, \mathrm{SAB} 1, \mathrm{SAB} 0$ |
| $4 \mathrm{Mb} / \mathrm{s}$ to $2 \mathrm{Mb} / \mathrm{s}$ | $4 \times 8$ | CAB5 to CAB0 (64 channel/inp. stream) | $\mathrm{SAB} 2, \mathrm{SAB} 1$ |
| $8 \mathrm{Mb} / \mathrm{s}$ to $2 \mathrm{Mb} / \mathrm{s}$ | $2 \times 8$ | CAB6 to CAB0 (128 channel/inp. stream) | SAB 2 |

Table 10 - CAB and SAB Bits Programming for Different I/O Rate Applications

Stream Pair Selection Register - Read/Write (ONLY PROVIDED IN THE 44 PIN PACKAGES)


[^3]Figure 7 - Stream Pair Selection (SPS) Register

[^4]Frame Input Offset Register - Read/Write


Figure 8 - Frame Input Offset (FIO) Register
$\mathrm{x}=$ Don't care

## Applications

## Switch Matrix Architectures

The MT8986 is an ideal device for designs of medium size switch matrix. For applications where voice and grouped data channels are transported within the same frame, the voice samples have to be time interchanged with a minimum delay while maintaining the integrity of grouped data. To guarantee the integrity of grouped data during switching and to provide a minimum delay for voice connections, the MT8986 provides the per-channel selection between variable and constant throughput delay. This can be selected by the $\overline{\mathrm{V}} / \mathrm{C}$ bit of the Connection Memory High locations.

Different connectivities at different data rates can be built to accommodate Non-Blocking matrices of up to 512 channels while maintaining the per channel selection of the device's throughput delay. Some examples of such Non-Blocking configurations are given in Figures 9 to 11.

For applications where voice and data samples are encoded into individual $64 \mathrm{~kb} / \mathrm{s}$ time-slots on an 8 kHz frame basis, the switch matrix can operate with time interchange procedures where only variable throughput delay is guaranteed. For such applications, the MT8986 device allows cost effective implementations of Non-Blocking matrices ranging up to 1024 channels. Figures 12 and 13 show the block diagram of implementations with NonBlocking capacities of 512 and 1024-channel, respectively.


Figure 9-512-Channel Switch with Serial Streams at 2.048 Mb/s


Figure 10-256-Channel Switch with Rate Conversion between 2.048 and 4.096 Mb/s


Figure 11-256-Channel Switch with Rate Conversion between 2.048 and 8.192 Mb/s


Figure 12-512-Channel Non-Blocking Switch Matrix with Serial Streams at 2.048 or 4.096 Mb/s


Figure 13-1024-Channel Non-Blocking Switch Matrix with Serial Streams at 2.048 Mb/s


Figure 14 - Interfacing the MT8986 to the $\mathbf{8 0 5 1}$ Microcontroller

## Interfacing MT8986 with 8051

The Intel 8051 is a very cost effective solution for many applications that do not require a large CPU interaction and processing overhead. However, in applications where 8051 is connected to peripherals operating on a synchronous 8 kHz time-base like the MT8986, some connectivity issues have to be addressed. The MT8986 may hold the CPU read/write cycle due to internal contention between the MT8986 microport and the internal serial to parallel and parallel to serial converters. Since the 8051 family of CPUs do not provide Data Ready type of inputs, some external logic and software intervention have to be provided between the MT8986 and the 8051 microcontrollers to allow read/write operation. The external logic described in Figure 14 is a block diagram of a logical connection between MT8986 and 8051. Its main function is to store the 8051 data during a write and the MT8986 data during a read.

For a write, MT8986 address is latched by the internal address latch on the falling edge of the ALE input. Whenever a read or write operation is done to the MT8986 device, the address decoded signal ( $\overline{\mathrm{MTA}}$ ) is used to latch or "freeze" the state of $\overline{R D}, \overline{W R}$, and the ALE signals, until the data acknow-ledge output signal is provided by the MT8986 device, releasing the latches for a new read/write cycle. Latch U5 is used to hold the 8051 data for a write until the CPU is ready to accept it (when DTA goes low). Latch U4 stores the MT8986 output data during a read cycle whenever DTA goes low. When writing to the MT8986, one write operation is sufficient. However, when reading MT8986, two read operations with the same address are required, with the second being valid.

Enough time need to be provided between two CPU accesses to allow the first access to complete; i.e., to allow for an internal MT8986 reaction over the first $\overline{R D} / \overline{W R}$ access. For a read operation, a minimum of 1220 ns have to be guaranteed between two successive accesses. For write, at least 800 ns has to be respected.

## Absolute Maximum Ratings*

|  | Parameter | Symbol | Min. | Max. | Units |
| :---: | :--- | :---: | :---: | :---: | :---: |
| 1 | $\mathrm{~V}_{\mathrm{DD}}-\mathrm{V}_{\mathrm{SS}}$ |  | -0.3 | 7 | V |
| 2 | Voltage on Digital Inputs | $\mathrm{V}_{\mathrm{I}}$ | $\mathrm{V}_{\mathrm{SS}}-0.3$ | $\mathrm{~V}_{\mathrm{DD}}+0.3$ | V |
| 3 | Voltage on Digital Outputs | $\mathrm{V}_{\mathrm{O}}$ | $\mathrm{V}_{\mathrm{SS}}-0.3$ | $\mathrm{~V}_{\mathrm{DD}}+0.3$ | V |
| 4 | Current at Digital Outputs | $\mathrm{I}_{\mathrm{O}}$ |  | 40 | mA |
| 5 | Storage Temperature | $\mathrm{T}_{\mathrm{S}}$ |  | -65 | +150 |
| ${ }^{\circ} \mathrm{C}$ |  |  |  |  |  |
| 6 | Package Power Dissipation | $\mathrm{P}_{\mathrm{D}}$ |  | 2 | W |

* Exceeding these values may cause permanent damage. Functional operation under these conditions is not implied.

Recommended Operating Conditions - Voltages are with respect to ground ( $\mathrm{V}_{\mathrm{SS}}$ ) unless otherwise stated.

|  | Characteristics | Sym. | Min. | Typ. ${ }^{\ddagger}$ | Max. | Units | Test Conditions |
| :---: | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Operating Temperature | $\mathrm{T}_{\mathrm{OP}}$ | -40 | 25 | +85 | ${ }^{\circ} \mathrm{C}$ |  |
| 2 | Positive Supply | $\mathrm{V}_{\mathrm{DD}}$ | 4.75 | 5.0 | 5.25 | V |  |
| 3 | Input Voltage | $\mathrm{V}_{\mathrm{I}}$ | 0 |  | $\mathrm{~V}_{\mathrm{DD}}$ | V |  |

$\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.
DC Electrical Characteristics - Voltages are with respect to ground $\left(\mathrm{V}_{\mathrm{Ss}}\right)$ unless otherwise stated.

|  |  | Characteristics | Sym. | Min. | Typ. ${ }^{\ddagger}$ | Max. | Units | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $\begin{gathered} \mathrm{I} \\ \mathrm{~N} \\ \mathrm{P} \\ \mathrm{U} \\ \mathrm{~T} \\ \mathrm{~S} \end{gathered}$ | Supply Current | $\mathrm{I}_{\mathrm{DD}}$ |  | 10 | 15 | mA | Outputs unloaded |
| 2 |  | Input High Voltage | $\mathrm{V}_{\mathrm{IH}}$ | 2.0 |  |  | V |  |
| 3 |  | Input Low Voltage | $\mathrm{V}_{\text {IL }}$ |  |  | 0.8 | V |  |
| 4 |  | Input Leakage (input pins) Input Leakage (I/O pins) | $\mathrm{I}_{\text {IL }}$ |  | 34 | $\begin{gathered} 5 \\ 100 \end{gathered}$ | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{I}}$ between $\mathrm{V}_{\text {SS }}$ and $\mathrm{V}_{\mathrm{DD}}$ |
| 5 |  | Input Pin Capacitance | $\mathrm{C}_{\text {I }}$ |  | 8 |  | pF |  |
| 6 | $\begin{aligned} & \mathrm{O} \\ & \mathrm{U} \\ & \mathrm{~T} \\ & \mathrm{P} \\ & \mathrm{U} \\ & \mathrm{~T} \\ & \mathrm{~S} \end{aligned}$ | Output High Voltage | $\mathrm{V}_{\mathrm{OH}}$ | 2.4 |  |  | V | $\mathrm{I}_{\mathrm{OH}}=10 \mathrm{~mA}$ |
| 7 |  | Output High Current | $\mathrm{I}_{\mathrm{OH}}$ | 10 | 15 |  | mA | Sourcing. $\mathrm{V}_{\mathrm{OH}}=2.4 \mathrm{~V}$ |
| 8 |  | Output Low Voltage | $\mathrm{V}_{\mathrm{OL}}$ |  |  | 0.4 | V | $\mathrm{I}_{\mathrm{OL}}=5 \mathrm{~mA}$ |
| 9 |  | Output Low Current | $\mathrm{I}_{\mathrm{OL}}$ | 5 | 10 |  | mA | Sinking. $\mathrm{V}_{\mathrm{OL}}=0.4 \mathrm{~V}$ |
| 10 |  | High Impedance Leakage | $\mathrm{I}_{\mathrm{OZ}}$ |  |  | 5 | $\mu \mathrm{A}$ | $\mathrm{V}_{\mathrm{O}}$ between $\mathrm{V}_{\text {SS }}$ and $\mathrm{V}_{\text {DD }}$ |
| 11 |  | Output Pin Capacitance | $\mathrm{C}_{0}$ |  | 8 |  | pF |  |

$\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.


Figure 15 - Output Test Load
AC Electrical Characteristics ${ }^{\dagger}$ - ST-BUS Timing (2.048 Mb/s) - Voltages are with respect to ground (VSS) unless otherwise stated.

|  | Characteristics | Sym. | Min. | Typ. $\ddagger$ | Max. | Units | Test Conditions |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Frame Pulse width | $\mathrm{t}_{\text {FRW }}$ |  | 244 |  | ns |  |
| 2 | Frame Pulse setup time | $\mathrm{t}_{\text {FRS }}$ | 10 |  | 190 | ns |  |
| 3 | Frame Pulse hold time | $\mathrm{t}_{\text {FRH }}$ | 20 |  | 190 | ns |  |
| 4 | STo delay Active to Active | $\mathrm{t}_{\text {DAA }}$ |  | 45 | 100 | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 5 | STi setup time | $\mathrm{t}_{\text {STIS }}$ | 20 |  |  | ns |  |
| 6 | STi hold time | $\mathrm{t}_{\text {STIH }}$ | 20 |  |  | ns |  |
| 7 | Clock period | $\mathrm{t}_{\mathrm{CLK}}$ | 190 | 244 | 300 | ns |  |
| 8 | CK Input Low | $\mathrm{t}_{\mathrm{CL}}$ | 85 | 122 | 150 | ns |  |
| 9 | CK Input High | $\mathrm{t}_{\mathrm{CH}}$ | 85 | 122 | 150 | ns |  |
| 10 | Clock Rise/Fall Time | $\mathrm{t}_{\mathrm{r}, \mathrm{t}_{\mathrm{f}}}$ |  |  | 10 | ns |  |

$\dagger$ Timing is over recommended temperature \& power supply voltages ( $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V} \pm 5 \%, \mathrm{~V}_{\mathrm{SS}}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=40$ to $85^{\circ} \mathrm{C}$ ).
$\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.


Figure 16 - ST-BUS Timing (CLKM bit=0)

AC Electrical Characteristics ${ }^{\dagger}$ - GCI Timing ( $2.048 \mathrm{Mb} / \mathbf{s}$ ) - Voltages are with respect to ground (VSS) unless otherwise stated.

|  | Characteristics | Sym. | Min. | Typ. ${ }^{\|c\|}$ | Max. | Units | Test Conditions |
| :---: | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Clock Period | $\mathrm{t}_{\mathrm{CK}}$ | 150 | 244 | 300 | ns |  |
| 2 | Pulse Width | $\mathrm{t}_{\mathrm{CL}}, \mathrm{t}_{\mathrm{CH}}$ | 73 | 122 | 150 | ns |  |
| 3 | Frame Width High | $\mathrm{t}_{\mathrm{WFH}}$ |  | 244 |  | ns |  |
| 4 | Frame Setup | $\mathrm{t}_{\mathrm{FRS}}$ | 10 |  | 190 | ns |  |
| 5 | Frame Hold | $\mathrm{t}_{\mathrm{FRH}}$ | 20 |  | 190 | ns |  |
| 6 | Data Delay/Clock Active to Active | $\mathrm{t}_{\mathrm{DAA}}$ |  | 45 | 100 | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 7 | Serial Input Setup | $\mathrm{t}_{\text {STIS }}$ | 20 |  |  | ns |  |
| 8 | Serial Input Hold | $\mathrm{t}_{\mathrm{STIH}}$ | 20 |  |  | ns |  |
| 9 | Clock Rise/Fall Time | $\mathrm{t}_{\mathrm{r},} \mathrm{t}_{\mathrm{f}}$ |  |  | 10 | ns |  |

$\dagger$ Timing is over recommended temperature \& power supply voltages ( $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V} \pm 5 \%, \mathrm{~V}_{\mathrm{SS}}=0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40$ to $\left.85^{\circ} \mathrm{C}\right)$.
$\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.


Figure 17-GCI Timing (CLKM bit=0)

AC Electrical Characteristics ${ }^{\dagger}$ - Serial Streams for ST-BUS and GCI Backplanes (2.048 Mb/s)

|  |  | Characteristics | Sym. | Min. | Typ. ${ }^{\ddagger}$ | Max. | Units | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $\begin{gathered} \mathrm{O} \\ \mathrm{U} \\ \mathrm{~T} \\ \mathrm{P} \\ \mathrm{U} \\ \mathrm{~T} \\ \mathrm{~S} \end{gathered}$ | STo0/9 Delay - Active to High Z | $\mathrm{t}_{\text {SAZ }}$ |  |  | 100 | ns | $\mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*}, \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 2 |  | STo0/9 Delay - High Z to Active | $\mathrm{t}_{\text {SZA }}$ |  |  | 100 | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 3 |  | Output Driver Enable Delay | $\mathrm{t}_{\text {OED }}$ |  |  | 65 | ns | $\mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*}, \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 4 |  | CSTo Output Delay | $\mathrm{t}_{\mathrm{XCD}}$ | 0 |  | 60 | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |

$\dagger$ Timing is over recommended temperature \& power supply voltages.
$\pm$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.

* High Impedance is measured by pulling to the appropriate rail with $\mathrm{R}_{\mathrm{L}}$, with timing corrected to cancel time taken to discharge $\mathrm{C}_{\mathrm{L}}$.


Figure 18 - Serial Outputs and External Control


Figure 19-Output Driver Enable

AC Electrical Characteristics - Serial Streams at 4.096 and $8.192 \mathrm{Mb} / \mathrm{s}$ - (refer to Figures 20-25)

|  | Characteristics | Sym. | Min. | Typ. | Max. | Units | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Clock Period  <br>  $4.096 \mathrm{Mb} / \mathrm{s}$ <br>  $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\mathrm{CK}}$ | $\begin{aligned} & 190 \\ & 110 \end{aligned}$ | $\begin{aligned} & 244 \\ & 122 \end{aligned}$ | $\begin{aligned} & 300 \\ & 150 \end{aligned}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 2 | Clock Pulse High  <br>  $4.096 \mathrm{Mb} / \mathrm{s}$ <br>  $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\mathrm{CH}}$ | $\begin{aligned} & 85 \\ & 50 \end{aligned}$ | $\begin{gathered} 122 \\ 60 \end{gathered}$ | $\begin{gathered} 150 \\ 70 \end{gathered}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 3 | Clock Pulse Low  <br>  $4.096 \mathrm{Mb} / \mathrm{s}$ <br>  $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\mathrm{CL}}$ | $\begin{aligned} & 85 \\ & 50 \end{aligned}$ | $\begin{gathered} 122 \\ 60 \end{gathered}$ | $\begin{gathered} 150 \\ 70 \end{gathered}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 4 | Frame Sync Setup <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  | $\mathrm{t}_{\mathrm{FS}}$ | $\begin{aligned} & 10 \\ & 10 \end{aligned}$ |  | $\begin{gathered} 190 \\ 90 \end{gathered}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 5 | Frame Sync Hold  <br>  $4.096 \mathrm{Mb} / \mathrm{s}$ <br>  $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\mathrm{FH}}$ | $\begin{aligned} & 20 \\ & 20 \end{aligned}$ |  | $\begin{gathered} 190 \\ 90 \end{gathered}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 6 | Frame Sync Width  <br>  $4.096 \mathrm{Mb} / \mathrm{s}$ <br>  $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\text {fW }}$ |  | $\begin{aligned} & 244 \\ & 122 \end{aligned}$ |  | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 7 | $\begin{array}{\|r\|} \hline \text { Valid Data Delay from CK Input } \\ 4.096 \mathrm{Mb} / \mathrm{s} \\ 8.192 \mathrm{Mb} / \mathrm{s} \\ \hline \end{array}$ | $\mathrm{t}_{\mathrm{DD}}$ |  | $\begin{aligned} & 40 \\ & 30 \end{aligned}$ | $\begin{aligned} & 80 \\ & 45 \end{aligned}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF} \\ & \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} \end{aligned}$ |
| 8 | Input Data Setup <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br>  | $\mathrm{t}_{\text {DS }}$ | $\begin{aligned} & 0 \\ & 0 \end{aligned}$ |  |  | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 9 | Input Data Hold  <br>  $4.096 \mathrm{Mb} / \mathrm{s}$ <br>  $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\mathrm{DH}}$ | $\begin{aligned} & 20 \\ & 20 \end{aligned}$ |  |  | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ |  |
| 10 | STo Delay from Active to High Z $\begin{aligned} & 4.096 \mathrm{Mb} / \mathrm{s} \\ & 8.192 \mathrm{Mb} / \mathrm{s} \end{aligned}$ | $\mathrm{t}_{\mathrm{AZ}}$ |  |  | $\begin{aligned} & 80 \\ & 45 \end{aligned}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*} \\ & \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*} \end{aligned}$ |
| 11 | STo Delay from High Z to Active <br> $4.096 \mathrm{Mb} / \mathrm{s}$ <br> $8.192 \mathrm{Mb} / \mathrm{s}$ | $\mathrm{t}_{\mathrm{zA}}$ |  |  | $\begin{aligned} & 80 \\ & 45 \end{aligned}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF} \\ & \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF} \end{aligned}$ |
| 12 | Output Drive Enable Delay $\begin{aligned} & 4.096 \mathrm{Mb} / \mathrm{s} \\ & 8.192 \mathrm{Mb} / \mathrm{s} \end{aligned}$ | $\mathrm{t}_{\text {OED }}$ |  |  | $\begin{aligned} & 65 \\ & 65 \end{aligned}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \end{aligned}$ | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*} \\ & \mathrm{C}_{\mathrm{L}}=50 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*} \end{aligned}$ |



Figure 20 - Serial Interface Timng (CLKM bit=1, DMO bit=0) - 4.096 and $8.192 \mathrm{Mb} / \mathrm{s}$

Note: For $8.192 \mathrm{Mb} / \mathrm{s}$ clock, only the positive polarity frame pulse is accepted by the MT8986 device.


Figure 21 - Output Driver Enable for Streams at 4.096 and 8.192 Mb/s


Figure $\mathbf{2 2}$ - Rate Conversion Mode (DMO bit=1) - $\mathbf{4} \mathbf{~ M b} / \mathrm{s}$ to $\mathbf{2 ~ M b / s}$


Figure 23 - Rate Conversion Mode (DMO bit=1)-2 Mb/s to $4 \mathrm{Mb} / \mathrm{s}$


Figure 24 - Rate Conversion Mode (DMO bit=1) - $\mathbf{8} \mathbf{~ M b / s}$ to $\mathbf{2 ~ M b / s}$


Figure 25 - Rate Conversion Mode (DMO bit=1) - $2 \mathrm{Mb} / \mathrm{s}$ to $\mathbf{8} \mathbf{~ M b} / \mathrm{s}$

AC Electrical Characteristics ${ }^{\dagger}$ - Intel/National- HPC Multiplexed Bus Mode - Voltages are with respect to ground (VSS) unless otherwise stated.

|  | Characteristics | Sym. | Min. | Typ. ${ }^{\ddagger}$ | Max. | Units | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | ALE pulse width | $\mathrm{t}_{\text {ALW }}$ | 20 |  |  | ns |  |
| 2 | Address setup from ALE falling | $\mathrm{t}_{\text {ADS }}$ | 8 |  |  | ns |  |
| 3 | Address hold from ALE falling | $\mathrm{t}_{\text {ADH }}$ | 9 |  |  | ns |  |
| 4 | $\overline{\mathrm{RD}}$ active after ALE falling | $\mathrm{t}_{\text {ALRD }}$ | 9 |  |  | ns |  |
| 5 | Data setup from $\overline{\text { DTA }}$ Low on Read | $\mathrm{t}_{\mathrm{DDR}}$ | 10 |  |  | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 6 | $\overline{\mathrm{CS}}$ hold after $\overline{\mathrm{RD}} / \overline{\mathrm{WR}}$ | $\mathrm{t}_{\text {CSRW }}$ | 0 |  |  | ns |  |
| 7 | $\overline{\mathrm{RD}}$ pulse width (fast read) | $\mathrm{t}_{\text {RW }}$ |  | 80 |  | ns |  |
| 8 | $\overline{\mathrm{CS}}$ setup from $\overline{\mathrm{RD}}$ | $\mathrm{t}_{\text {CSR }}$ | 0 |  |  | ns |  |
| 9 | Data hold after $\overline{\mathrm{RD}}$ | $\mathrm{t}_{\mathrm{DHR}}$ | 10 | 50 | 90 | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega *$ |
| 10 | $\overline{\mathrm{WR}}$ pulse width (fast write) | $\mathrm{t}_{\text {ww }}$ |  | 90 |  | ns |  |
| 11 | $\overline{\mathrm{WR}}$ delay after ALE falling | $\mathrm{t}_{\text {ALWR }}$ | 10 |  |  | ns |  |
| 12 | $\overline{\mathrm{CS}}$ setup from $\overline{\mathrm{WR}}$ | $\mathrm{t}_{\text {CSW }}$ | 0 |  |  | ns |  |
| 13 | Data setup from $\overline{\mathrm{WR}}$ (fast write) | $\mathrm{t}_{\text {DSW }}$ | 90 |  |  | ns |  |
| 14 | Valid Data Delay on write (slow write) | $\mathrm{t}_{\text {SWD }}$ |  |  | 122 | ns |  |
| 15 | Data hold after $\overline{\mathrm{WR}}$ inactive | $\mathrm{t}_{\text {DHW }}$ | 8 |  |  | ns |  |
| 16 | Acknowledgement Delay: <br> Reading Data Memory Reading/Writing Conn. Memories Writing to Control \& Mode Reg. Reading from Control \& Mode Reg. | $\mathrm{t}_{\text {AKD }}$ |  | $\begin{gathered} 560 \\ 300 / 370 \\ 47 \\ 60 \end{gathered}$ | $\begin{gathered} 1220 \\ 730 / 800 \\ 95 \\ 125 \end{gathered}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \\ & \mathrm{~ns} \\ & \mathrm{~ns} \end{aligned}$ | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 17 | Acknowledgement Hold Time | $\mathrm{t}_{\text {AKH }}$ | 10 | 60 | 110 | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega^{*}$ |

$\dagger$ Timing is over recommended temperature \& power supply voltages.
$\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.

* High Impedance is measured by pulling to the appropriate rail with $\mathrm{R}_{\mathrm{L}}$, with timing corrected to cancel time taken to discharge $\mathrm{C}_{\mathrm{L}}$.


Figure 26 - Intel/National Multiplexed Bus Timing

AC Electrical Characteristics ${ }^{\dagger}$ - Motorola Multiplexed Bus Mode - Voltages are with respect to ground (VSS) unless otherwise stated.

|  | Characteristics | Sym. | Min. | Typ. ${ }^{\text { }}$ | Max. | Units | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | AS pulse width | $\mathrm{t}_{\text {asw }}$ | 80 |  |  | ns |  |
| 2 | Address setup from AS falling | $\mathrm{t}_{\text {ADS }}$ | 8 |  |  | ns |  |
| 3 | Address hold from AS falling | $\mathrm{t}_{\text {ADH }}$ | 9 |  |  | ns |  |
| 4 | Data setup from $\overline{\text { DTA }}$ Low on Read | $\mathrm{t}_{\text {DDR }}$ | 10 |  |  | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 5 | $\overline{\mathrm{CS}}$ hold after DS falling | $\mathrm{t}_{\text {CSH }}$ | 0 |  |  | ns |  |
| 6 | $\overline{\text { CS }}$ setup from DS rising | $\mathrm{t}_{\mathrm{css}}$ | 0 |  |  | ns |  |
| 7 | Data hold after write | $\mathrm{t}_{\text {DHW }}$ | 8 |  |  | ns |  |
| 8 | Data setup from DS - write (fast write) | $\mathrm{t}_{\text {Dws }}$ | 25 |  |  | ns |  |
| 9 | Valid Data Delay on write (slow write) | $\mathrm{t}_{\text {swd }}$ |  |  | 122 | ns |  |
| 10 | $\mathrm{R} / \overline{\mathrm{W}}$ setup from DS rising | $\mathrm{t}_{\mathrm{RWS}}$ | 60 |  |  | ns |  |
| 11 | $\mathrm{R} / \overline{\mathrm{W}}$ hold after DS falling | $\mathrm{t}_{\text {RWH }}$ | 9 |  |  | ns |  |
| 12 | Data hold after read | $\mathrm{t}_{\text {DHR }}$ | 10 | 50 | 90 | ns | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega * \end{aligned}$ |
| 13 | DS delay after AS falling | $\mathrm{t}_{\text {DSH }}$ | 10 |  |  | ns |  |
| 14 | Acknowledgement Delay: <br> Reading Data Memory Reading/Writing Conn. Memories Writing Control \& Mode Regs. Reading from Control \& Mode Regs. | $\mathrm{t}_{\text {AKD }}$ |  | $\begin{gathered} 560 \\ 300 / 370 \\ 47 \\ 73 \end{gathered}$ | $\begin{gathered} 1220 \\ 730 / 800 \\ 95 \\ 125 \end{gathered}$ | $\begin{aligned} & \text { ns } \\ & \text { ns } \\ & \text { ns } \\ & \text { ns } \end{aligned}$ | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 15 | Acknowledgement Hold Time | $\mathrm{t}_{\text {AKH }}$ | 10 | 60 | 110 | ns | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega * \end{aligned}$ |

$\dagger$ Timing is over recommended temperature \& power supply voltages.
$\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.

* High Impedance is measured by pulling to the appropriate rail with $\mathrm{R}_{\mathrm{L}}$, with timing corrected to cancel time taken to discharge $\mathrm{C}_{\mathrm{L}}$.


Figure 27 - Motorola Multiplexed Bus Timing

AC Electrical Characteristics ${ }^{\dagger}$ - Motorola Non-Multiplexed Bus Mode - Voltages are with respect to ground (VSS) unless otherwise stated.

|  | Characteristics | Sym. | Min. | Typ. ${ }^{\ddagger}$ | Max. | Units | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | $\overline{\mathrm{CS}}$ Setup from DS rising | $\mathrm{t}_{\text {CSS }}$ | 0 |  |  | ns |  |
| 2 | $\mathrm{R} / \overline{\mathrm{W}}$ Setup from DS rising | $\mathrm{t}_{\text {RWS }}$ | 30 |  |  | ns |  |
| 3 | Add setup from DS rising | $\mathrm{t}_{\text {ADS }}$ | 5 |  |  | ns |  |
| 4 | $\overline{\mathrm{CS}}$ hold after DS falling | $\mathrm{t}_{\mathrm{CSH}}$ | 0 |  |  | ns |  |
| 5 | $\mathrm{R} / \overline{\mathrm{W}}$ hold after DS falling | $\mathrm{t}_{\text {RWH }}$ | 5 |  |  | ns |  |
| 6 | Add hold after DS falling | $\mathrm{t}_{\text {ADH }}$ | 5 |  |  | ns |  |
| 7 | Data setup from $\overline{\text { DTA }}$ Low on Read | $\mathrm{t}_{\text {DDR }}$ | 10 |  |  | ns | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 8 | Data hold on read | $\mathrm{t}_{\mathrm{DHR}}$ | 10 | 50 | 90 | ns | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega * \end{aligned}$ |
| 9 | Data setup on write (fast write) | $\mathrm{t}_{\text {DSW }}$ | 20 |  |  | ns |  |
| 10 | Valid Data Delay on write (slow write) | $\mathrm{t}_{\text {SWD }}$ |  |  | 122 | ns |  |
| 11 | Data hold on write | $\mathrm{t}_{\text {DHW }}$ | 8 |  |  | ns |  |
| 12 | Acknowledgement Delay: Reading Data Memory Reading/Writing Conn. Memories Writing Control \& Mode Regs. Reading from Control \& Mode Regs. | $\mathrm{t}_{\text {AKD }}$ |  | $\begin{gathered} 560 \\ 300 / 370 \\ 47 \\ 70 \end{gathered}$ | $\begin{gathered} 1220 \\ 730 / 800 \\ 95 \\ 155 \end{gathered}$ | $\begin{aligned} & \mathrm{ns} \\ & \mathrm{~ns} \\ & \mathrm{~ns} \\ & \mathrm{~ns} \end{aligned}$ | $\mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}$ |
| 13 | Acknowledgement Hold Time | $\mathrm{t}_{\text {AKH }}$ | 10 | 60 | 110 | ns | $\begin{aligned} & \mathrm{C}_{\mathrm{L}}=150 \mathrm{pF}, \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{~K} \Omega * \end{aligned}$ |

[^5]

Figure 28 - Motorola Non-Multiplexed Bus Timing



## Notes:



Seating Plane

1. All dimensions and tolerances conform to ANSI Y14.5M-1982
2. Dimensions D1 and E1 do not include mould protrusions.

Allowable mould protrusion is $0.010^{\prime \prime}$ per side. Dimensions D1 and E1 include mould protrusion mismatch and are determined at the parting line, that is D1 and E1 are measured at the extreme material condition at the upper or lower parting line.
3. Controlling dimensions in Inches.
4. " $N$ " is the number of terminals.
5. Not To Scale
6. Dimension R required for $120^{\circ}$ minimum bend.



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[^0]:    ** 44 pin packages only

[^1]:    $\mathrm{x}=$ Don't care

[^2]:    *     - only in 44 pin package

[^3]:    These bits are only used when the Switching Configuration bits enable stream pair selection capability (SCB 1-0 = 10) and the Input Data Rate Selection bits enable $2 \mathrm{Mb} /$ s operation (IDR- $0=00$ ). In all other modes, the contents of this register are ignored.

[^4]:    $\mathrm{x}=$ Don't care

[^5]:    $\dagger$ Timing is over recommended temperature \& power supply voltages .
    $\ddagger$ Typical figures are at $25^{\circ} \mathrm{C}$ and are for design aid only: not guaranteed and not subject to production testing.

    * High Impedance is measured by pulling to the appropriate rail with $\mathrm{R}_{\mathrm{L}}$, with timing corrected to cancel time taken to discharge $\mathrm{C}_{\mathrm{L}}$.

