600 kHz PWM/PFM Step-Down DC-DC Controller

The NCP1550 is a monolithic micropower high frequency voltage mode step-down controller IC, specially designed for battery operated hand-held electronic products. With appropriate external P-type MOSFET, the device can provide up to 2.0 A loading current with high conversion efficiency. The device operates in Constant–Frequency PWM mode at normal operation, that ensures low output ripple noise, and which will automatically switch to PFM mode at low output loads for higher efficiency. Additionally, value–added features of Chip Enable to reduce IC Off–State current and integrated feedback resistor network, make it the best choice for portable applications. The device is designed to operate for voltage regulation with minimum external components and board space. This device is available in a TSOP–5 package with six standard output voltage options.

Features

- Pb–Free Packages are Available
- High Efficiency 92%, Typical
- $\bullet\,$ Low Quiescent Bias Current of 50 μA (Typical at PFM Mode with No Load)
- Output Voltage Options from 1.8 V to 3.3 V with High Accuracy ± 2.0%
- Low Output Voltage Ripple, 50 mV, Typical
- PWM Switching Frequency at 600 kHz
- Automatic PWM/PFM Switchover at Light Load Condition
- Very Low Dropout Operation, 100% Max. Duty Cycle
- Chip Enable Pin with On-Chip 150 nA Pullup Current Source
- Low Shutdown Current, 0.3 µA, Typical
- Input Voltage Range from 2.45 V to 5.5 V
- Built-in Soft-Start
- Internal Undervoltage Lockout (UVLO) Protection
- Low Profile and Minimum External Components
- Micro Miniature TSOP-5 Package

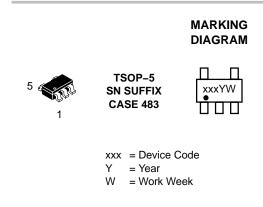
Typical Applications

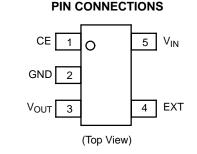
- Personal Digital Assistant (PDA)
- Camcorders and Digital Still Camera
- Hand–Held Instrument
- Distributed Power System
- Computer Peripheral
- Conversion from Four NiMH or NiCd or One Lithium–ion Cells to 3.3 V/1.8 V



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ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 16 of this data sheet.

1

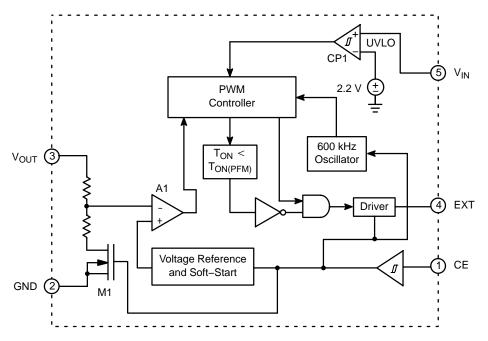


Figure 1. Simplified Block Diagram

PIN FUNCTION DESCRIPTIONS

Symbol	Description
CE	Chip Enable pin, active high (internal pullup current source). By connecting this pin to GND, the switching operation of the controller will be stopped.
GND	Ground Connection
V _{OUT}	Output voltage monitoring input. This pin must be connected to the regulated output node as a feedback to on-chip control circuitry. V _{OUT} is internally connected to the on-chip voltage divider that determines the output voltage level.
EXT	Gate drive for external P–MOSFET
V _{IN}	Power supply input
	CE GND V _{OUT} EXT

MAXIMUM RATINGS ($T_A = 25^{\circ}C$ unless otherwise noted)

Rating	Symbol	Value	Unit
Device Power Supply, V _{IN} (Pin 5)	V _{IN}	-0.3 to 6.0	V
Input/Output Pins CE (Pin 1) V _{OUT} (Pin 3) EXT (Pin 4)	V _{CE} V _{OUT} V _{EXT}	-0.3 to 6.0 -0.3 to 6.0 -0.3 to 6.0	V
Thermal Characteristics TSOP–5 Plastic Package, Case 483–01 Thermal Resistance, Junction–to–Air	R _{θJA}	250	°C/W
Operating Junction Temperature Range	Τ _J	-40 to +150	°C
Operating Ambient Temperature Range	T _A	-40 to +85	°C
Storage Temperature Range	T _{stg}	-55 to +150	°C

Maximum ratings are those values beyond which device damage can occur. Maximum ratings applied to the device are individual stress limit values (not normal operating conditions) and are not valid simultaneously. If these limits are exceeded, device functional operation is not implied, damage may occur and reliability may be affected. NOTE: ESD data available upon request.

1. This device series contains ESD protection and exceeds the following tests:

- Human Body Model (HBM) ±2.0 kV per JEDEC standard: JESD22-A114. Machine Model (MM) ±200V per JEDEC standard: JESD22-A115.
- Latchup Current Maximum Rating: 150 mA per JEDEC standard: JESD78.
 Moisture Sensitivity Level (MSL): 1 per IPC/JEDEC standard: J–STD–020A.

ELECTRICAL CHARACTERISTICS (V _{IN} = 5.0 V, T _A = 25°C for typical value, $-40°C \le T_A \le 85°C$ for min/max values unless	
otherwise noted.)	

Symbol	Min	Тур	Мах	Unit
V _{IN}	2.45	-	5.50	V
V _{OUT}	1.764 1.862 2.450 2.646 2.940 3.234	1.8 1.9 2.5 2.7 3.0 3.3	1.836 1.938 2.550 2.754 3.060 3.366	V
I _{VOUT}		2.5 2.5 2.5 2.5 2.5 2.5 2.5	4.0 4.0 4.0 4.0 4.0 4.0	μΑ
$V_{OUT/}\Delta V_{T}$	-	100	-	ppm/°C
I _{DD}		50 50 50 50 50 50	80 80 80 80 80 80	μΑ
I _{OFF}	- - - -	0.3 0.3 0.3 0.3 0.3 0.3	0.5 0.5 0.5 0.5 0.5 0.5	μΑ
<u> </u>				
F _{OSC}	510	600	690	kHz
$F_{OSC}/\Delta T_A$	_	0.11	-	%/°C
			- 0.3 Fosc 510 600	- 0.3 0.5 Fosc 510 600 690

Frequency Temperature Coefficient ($T_A = -40^{\circ}C$ to $85^{\circ}C$)	$\Delta F_{OSC} / \Delta T_A$	-	0.11	-	%/°C
Maximum Duty Cycle	D _{MAX}	100	-	-	%
PWM/PFM Switchover ON Time Threshold (Note 4)	T _{ON(PFM)}	167	320	500	ns
Soft-Start Delay Time (Note 4)	T _{ss}	-	8.0	-	ms
Protection Delay Time (Auto Restart)	T _{prot}	-	8.0	-	ms

OUTPUT DRIVE (PIN 4)

EXT "H" Output Current ($V_{EXT} = V_{IN} - 0.4 V$)	I _{EXTH}	-	-60	-	mA
EXT "L" Output Current (V _{EXT} = 0.4 V)	I _{EXTL}	-	100	-	mA
EXT "L–H" Rise Time (C_{LOAD} = 1000 pF) (V_{IN} = 5.0 V)	Tr	-	65	-	ns
EXT "H–L" Fall Time (C_{LOAD} = 1000 pF) (V_{IN} = 5.0 V)	T _f	-	40	-	ns
EXT "L–H" Rise Time (C_{LOAD} = 5.0 nF) (V_{IN} = 5.0 V)	Tr	-	140	-	ns
EXT "H–L" Fall Time (C_{LOAD} = 5.0 nF) (V_{IN} = 5.0 V)	T _f	-	90	-	ns

4. PWM/PFM Switchover ON Time Threshold min/max guaranteed by design only.

ELECTRICAL CHARACTERISTICS (continued) (V_{IN} = 5.0 V, T_A = 25°C for typical value, $-40°C \le T_A \le 85°C$ for min/max values unless otherwise noted.)

Characteristic	Symbol	Min	Тур	Max	Unit	
CE (PIN 1)						
CE "H" Input Voltage	V _{CEH}	1.3	_	-	V	
CE "L" Input Voltage	V _{CEL}	-	-	0.3	V	
CE "H" Input Current ($V_{IN} = V_{CE} = 5.0 \text{ V}$)	I _{CEH}	-0.5	0	0.5	μΑ	
CE "L" Input Current (V _{IN} = 5.0, V _{CE} = 0 V)	I _{CEL}	-0.5	0.15	0.5	μΑ	
Undervoltage Lockout						
Undervoltage Lockout Threshold	V _{UVLO}	1.60	2.20	2.40	V	
Undervoltage Lockout Hysteresis	V _{UVLO_HYS}	-	50	-	mV	

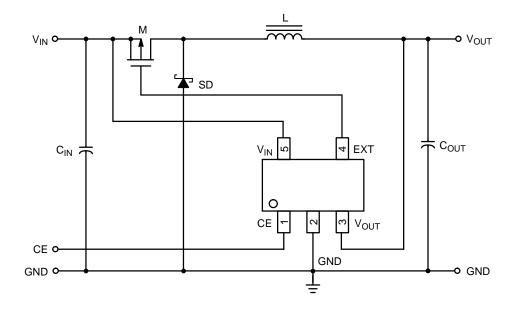
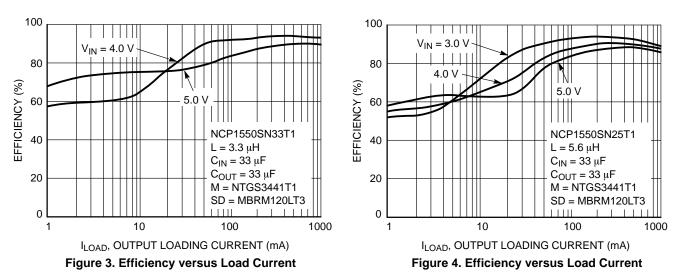


Figure 2. Typical Application Diagram



TYPICAL OPERATING CHARACTERISTICS

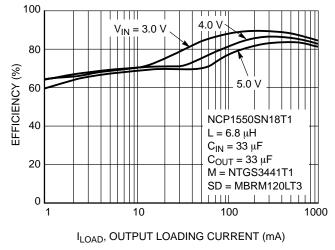
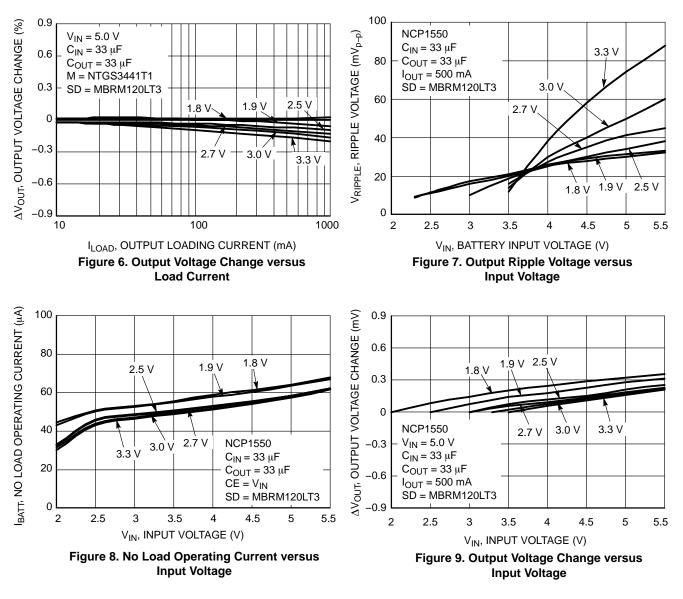
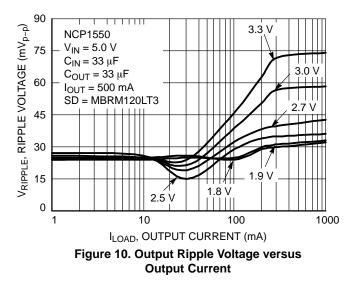
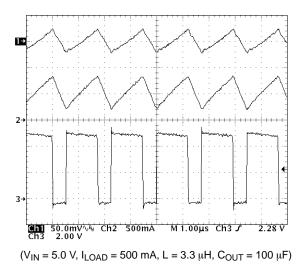


Figure 5. Efficiency versus Load Current

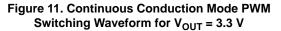


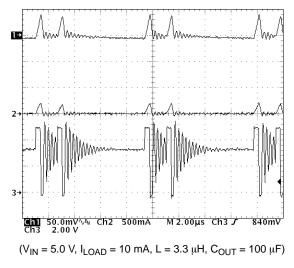
TYPICAL OPERATING CHARACTERISTICS





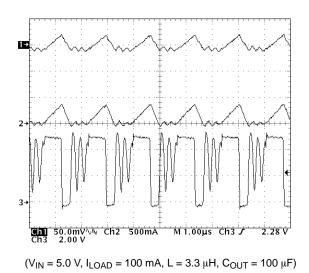
Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division





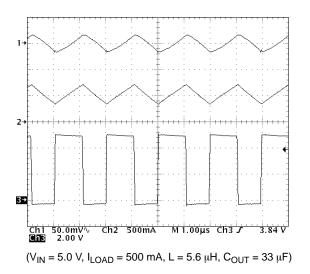
Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division

Figure 13. Discontinuous Conduction Mode PFM Switching Waveform for V_{OUT} = 3.3 V



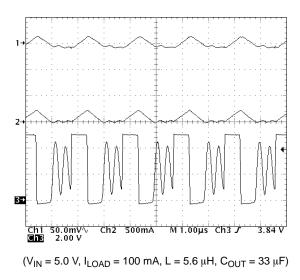
Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division

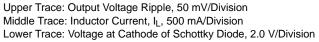
Figure 12. Discontinuous Conduction Mode PWM Switching Waveform for V_{OUT} = 3.3 V

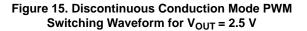


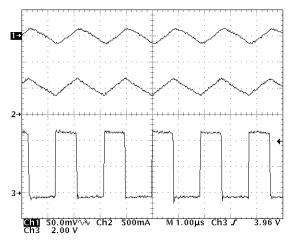
Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division

Figure 14. Continuous Conduction Mode PWM Switching Waveform for V_{OUT} = 2.5 V





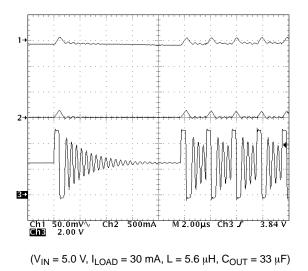




(V_{IN} = 5.0 V, I_{LOAD} = 500 mA, L = 6.8 μ H, C_{OUT} = 33 μ F)

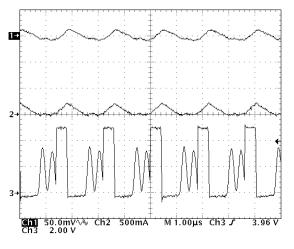
Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division

Figure 17. Continuous Conduction Mode PWM Switching Waveform for V_{OUT} = 1.8 V



Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division

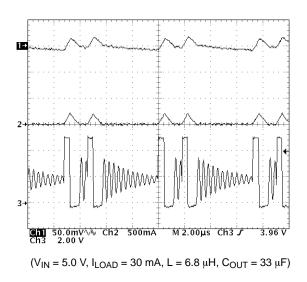
Figure 16. Discontinuous Conduction Mode PFM Switching Waveform for V_{OUT} = 2.5 V

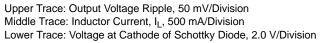


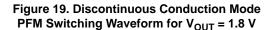
(V_{IN} = 5.0 V, I_{LOAD} = 60 mA, L = 6.8 μ H, C_{OUT} = 33 μ F)

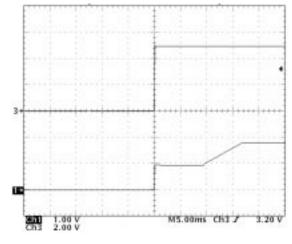
Upper Trace: Output Voltage Ripple, 50 mV/Division Middle Trace: Inductor Current, I_L, 500 mA/Division Lower Trace: Voltage at Cathode of Schottky Diode, 2.0 V/Division

Figure 18. Discontinuous Conduction Mode PWM Switching Waveform for V_{OUT} = 1.8 V









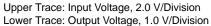
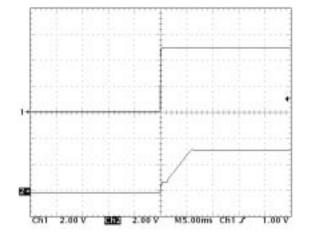
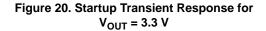
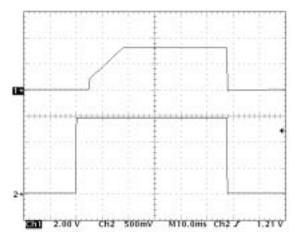


Figure 21. Startup Transient Response for V_{OUT} = 1.8 V

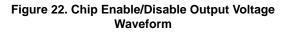


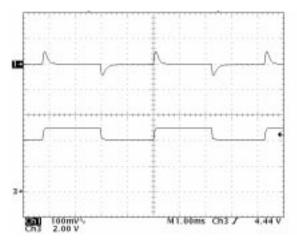
Upper Trace: Input Voltage, 2.0 V/Division Lower Trace: Output Voltage, 2.0 V/Division





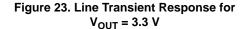
Upper Trace: Output Voltage Waveform, 2.0 V/Division Lower Trace: Chip Enable/Disable Pin Waveform, 0.5 V/Division

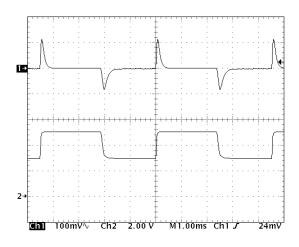




(V_{IN} = 4.0 to 5.0 V, L = 3.3 $\mu H,$ C_{OUT} = 33 $\mu F,$ I_{LOAD} = 1.0 A)

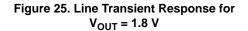
Upper Trace: Output Voltage Ripple, 100 mV/Division Lower Trace: Input Voltage, 2.0 V/Division

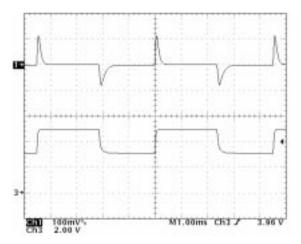




(V_{IN} = 3.0 to 5.0 V, L = 6.8 $\mu H,$ C_{OUT} = 33 $\mu F,$ I_{LOAD} = 1.0 A)

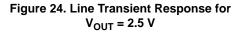
Upper Trace: Output Voltage Ripple, 100 mV/Division Lower Trace: Input Voltage, V_{IN} , 2.0 V/Division

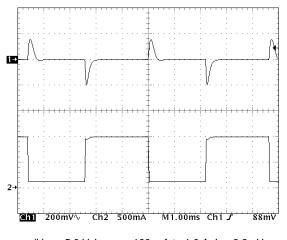




(V_{IN} = 3.0 to 5.0 V, L = 5.6 $\mu H,$ C_{OUT} = 33 $\mu F,$ I_{LOAD} = 1.0 A)

Upper Trace: Output Voltage Ripple, 100 mV/Division Lower Trace: Input Voltage, 2.0 V/Division

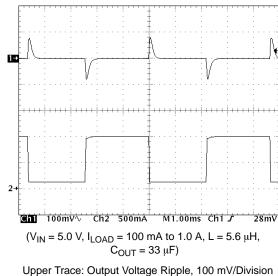


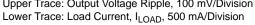


(V_{IN} = 5.0 V, I_{LOAD} = 100 mA to 1.0 A, L = 3.3 $\mu H,$ C_{OUT} = 33 $\mu F)$ Upper Trace: Output Voltage Ripple, 200 mV/Division

Lower Trace: Load Current, I_{LOAD}, 500 mA/Division

Figure 26. Load Transient Response for V_{OUT} = 3.3 V





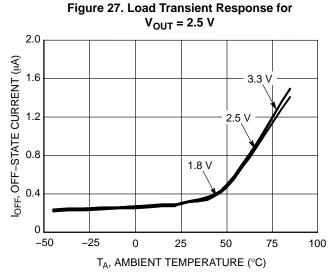
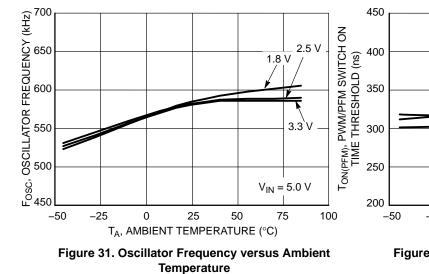
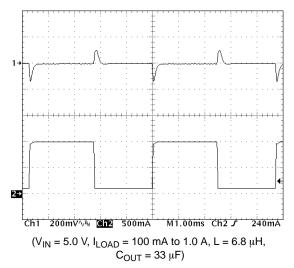
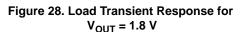


Figure 29. Off–Stage Current versus Ambient Temperature





Upper Trace: Output Voltage Ripple, 100 mV/Division Lower Trace: Load Current, I $_{LOAD}$, 500 mA/Division



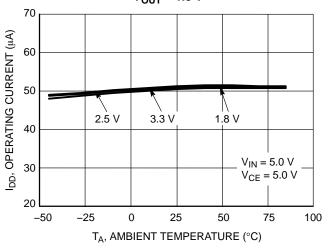
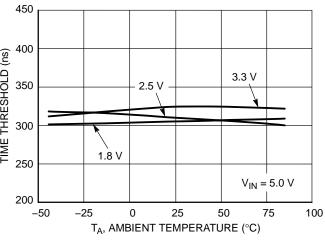
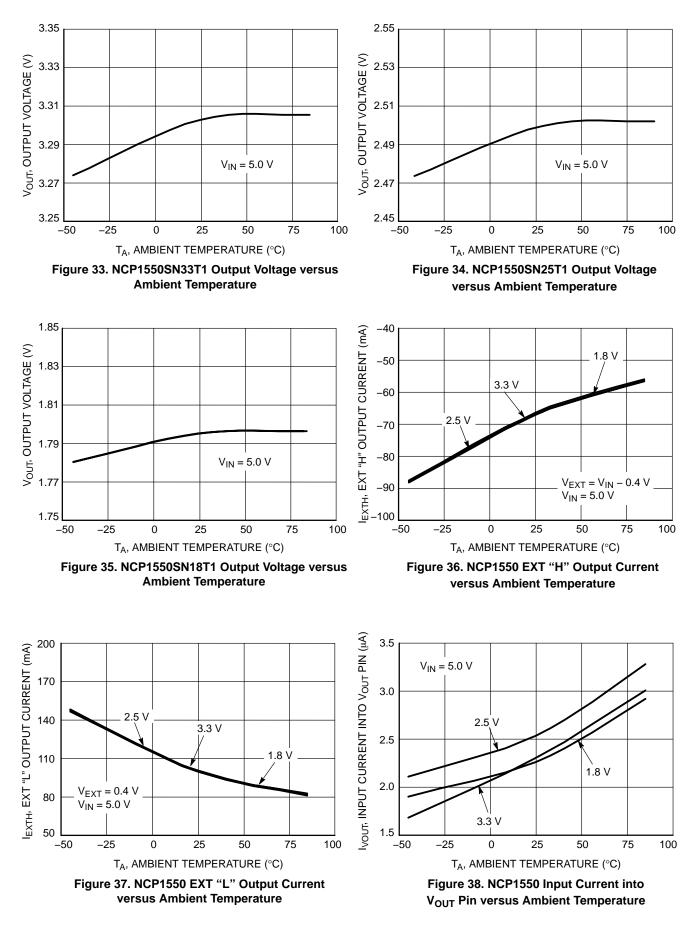


Figure 30. Operating Current versus Ambient Temperature







DETAILED OPERATING DESCRIPTION

Detailed Operating Description

The NCP1550 series are step-down (Buck) DC-DC controllers designed primarily for use in portable applications powered by battery cells. With an appropriate external P-channel MOSFET connected, the device can provide up to 2 A loading current with high conversion efficiency. The NCP1550 series using an unique control scheme combines the advantages of Pulse-Frequency-Modulation (PFM) that can provide excellent efficiency even at light loading conditions and Constant-Frequency Pulse-Width-Modulation that can achieve high efficiency and low output voltage ripple at heavy loads. The NCP1550 working at high switching frequency makes it possible to use small size surface mount inductor and capacitors to reduce PCB area and provide better interference handling for noise sensitive applications. The simplified functional blocks of the device are shown in Figure 1 and descriptions for each of the functions are given below.

The Internal Oscillator

An oscillator that governs the switching of a PWM control cycles is required. NCP1550 have an internal Fixed–Frequency oscillator. The oscillator frequency is trimmed to 600 kHz with an accuracy of $\pm 15\%$. All other timing signals needed for operation are derived from this oscillator signal.

Voltage Reference and Soft-Start

An internal high accuracy voltage reference is included in NCP1550. This reference voltage is connected to the inverting input terminal of the error amplifier, A1, which compared with portion of the output voltage, V_{OUT} derived from an integrated voltage divider with precise trimming to give the required output voltage at ±2% accuracy. NCP1550 also comes with a built–in soft–start circuit that controls the ramping up of the internal reference voltage during the power–up of the converter. This function effectively enables the output voltage to rise gradually over the specified soft–start time, 8 msec typical. This prevents the output voltage from overshooting during start–up of the converter.

Voltage Mode Pulse–Width–Modulation (PWM) Control Scheme

For normal operation, NCP1550 is working in Constant–Frequency Pulse–Width–Modulation (PWM) Voltage Mode Control. The controller operates with the internal oscillator, which generates the required ramp function to compare with the output of the error amplifier, A1. The error amplifier compares the internally divided–down output voltage with the voltage reference to produce an error voltage at its output. This error voltage is compared with the ramp function to generate the control pulse to drive the external power switch. On a cycle–by–cycle basis, the greater the error voltage, the longer the switch is held on. Hence, corresponding corrective action will be made to keep the output voltage within regulation. Constant–Frequency PWM reduces output voltage ripple and noise, which is one of the important characteristics for noise sensitive communication applications. The high switching frequency allows small size surface mount components to improve layout compactness and reduce PC board area, and eliminate audio and emission interference.

Power-Saving Pulse-Frequency-Modulation (PFM) Control Scheme

While the loading is decreasing, the converter enters the Discontinuous Conduction Mode (DCM) operation, which means the inductor current will decrease to zero before the next switching cycle starts. In DCM operation, the ON time for each switching cycle will decrease significantly when the output current decreases. In order to maintain a high conversion efficiency even at light load conditions, the ON time for each switching cycle is closely monitored and for any ON time smaller than the preset value, 320 nsec, the switching pulse will be skipped. As a result, when the loading current is small, the converter will be operating in a "Constant ON time (320 nsec nominal), variable OFF time" Pulse-Frequency Modulation (PFM) mode. This innovative control scheme improves the conversion efficiency for the system at light load and standby operating conditions hence extend the operating life of the battery.

Low Power Shutdown Mode

NCP1550 can be disabled whenever the CE pin (Pin 1) is tied to GND. In shutdown, the internal reference, oscillator, control circuitry, driver and internal feedback voltage divider are turned off and the output voltage falls to 0 V. During the shutdown mode, as most of the internal functions are stopped and current paths are cut–off, the device consume extremely small current in this condition.

Under-Voltage Lockout (UVLO)

To prevent operation of the P–Channel MOSFET below safe input voltage levels, an Undervoltage Lockout is incorporated into the NCP1550. When the input supply voltage drops below approximately 2.2 V, the comparator, CP1 will turn–off the control circuitry and shut the converter down.

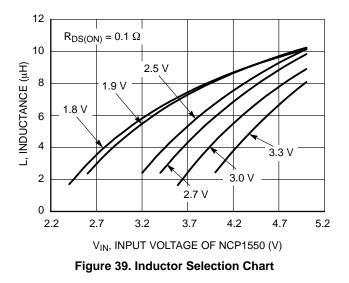
APPLICATIONS INFORMATION

Inductor Value Calculation

Selecting the proper inductance is a trade–off between inductor's physical size, transient respond and power conversion requirements. Lower value inductor saves cost, PC board space and providing faster transient response, but result in higher ripple current and core losses. Considering an application with loading current, $I_{OUT} = 0.5$ A and the inductor ripple current, $I_{L-RIPPLE(P-P)}$ is designed to be less than 40% of the load current, i.e. 0.5 A x 40% = 0.2 A. The relationship between the inductor value and inductor ripple current is given by,

$$L = \frac{T_{ON} * (V_{IN} - R_{DS}(ON) \times I_{OUT} - V_{OUT})}{I_{L} - RIPPLE(P - P)} \quad (eq. 1)$$

Where $R_{DS(ON)}$ is the ON resistance of the external P-channel MOSFET. Figure 39 is a plot for recommended inductance against nominal input voltage for different output options.



P-Channel Power MOSFET Selection

An external P–Channel power MOSFET must be used with the NCP1550. The key selection criteria for the power MOSFET are the gate threshold, V_{GS} , the "ON" resistance, $R_{DS(ON)}$ and its total gate charge, Q_T . For low input voltage operation, we need to select a low gate threshold device that can work down to the minimum input voltage level. $R_{DS(ON)}$ determines the conduction losses for each switching cycle, the lower the ON resistance, the higher the efficiency can be achieved. A power MOSFET with lower gate charge can give lower switching losses but the fast transient can cause unwanted EMI to the system. Compromise in between is required during the design stage. For 1.0 A and 2.0 A load current, NTGS3441T1 and NTGS3443T1 are tested to be appropriate for most applications.

Flywheel Diode Selection

The flywheel diode is turned on and carries load current during the off time. The average diode current depends on the P–Channel switch duty cycle. At high input voltages, the diode conducts most of the time. In case of V_{IN} approaches V_{OUT} , the diode conducts only a small fraction of the cycle. While the output terminals are shorted, the diode will subject to its highest stress. Under this condition, the diode must be able to safely handle the peak current circulating in the loop. So, it is important to select a flywheel diode that can meet the diode peak current and average power dissipation requirements. Under normal conditions, the average current conducted by the flywheel diode is given by:

$$I_{D} = \frac{V_{IN} - V_{OUT}}{V_{IN} + V_{F}} \times I_{OUT}$$
 (eq. 2)

Where I_D is the average diode current and V_F is the forward diode voltage drop.

A fast switching diode must also be used to optimize efficiency. Schottky diodes are a good choice for low forward drop and fast switching times.

Input and Output Capacitor Selection (CIN and COUT)

In continuous mode operation, the source current of the P–Channel MOSFET is a square wave of duty cycle $(V_{OUT} + V_F)/V_{IN}$. To prevent large input voltage transients, a low ESR input capacitor that can support the maximum RMS input current must be selected. The maximum RMS input current, $I_{RMS(MAX)}$ can be estimated by the equation in below:

$$|\text{RMS}(\text{MAX}) \approx |\text{OUT} \times \frac{\text{VOUT}(\text{VIN} - \text{VOUT})^{\frac{1}{2}}}{\text{VIN}}$$
 (eq. 3)

Above estimation has a maximum value at $V_{IN} = 2V_{OUT}$, where $I_{RMS(MAX)} = I_{OUT}/2$. As a general practice, this simple worst–case condition is used for design.

Selection of the output capacitor, C_{OUT} is primarily governed by the required effective series resistance (ESR) of the capacitor. Typically, once the ESR requirement is met, the capacitance will be adequate for filtering. The output voltage ripple, V_{RIPPLE} is approximated by:

$$V_{\text{RIPPLE}} \approx I_{\text{L}} - \text{RIPPLE}(P - P) \\ \times (\text{ESR} + \frac{1}{4 \text{ FOSCCOUT}}) \quad ^{(\text{eq. 4})}$$

Where F_{OSC} is the switching frequency and ESR is the effective series resistance of the output capacitor.

From equation (4), it can be noted that the output voltage ripple contributed by two parts. For most of the case, the major contributor is the capacitor ESR. Ordinary aluminum–electrolytic capacitors have high ESR and should be avoided. Higher quality Low ESR

aluminum-electrolytic capacitors are acceptable and relatively inexpensive. For even better performance, Low ESR tantalum capacitors should be used. Surface-mount tantalum capacitors are better and provide neat and compact solution for space sensitive applications.

PCB Layout Recommendations

Good PCB layout plays an important role in switching mode power conversion. Careful PCB layout can help to minimize ground bounce, EMI noise and unwanted feedbacks that can affect the performance of the converter. Suggested hints below can be used as a guideline in most situations.

Grounding

Star-ground connection should be used to connect the output power return ground, the input power return ground and the device power ground together at one point. All high current running paths must be thick enough for current flowing through and producing insignificant voltage drop along the path. Feedback signal path must be separated from the main current path and sensing directly at the anode of the output capacitor.

Components Placement

Power components, i.e. input capacitor, inductor and output capacitor, must be placed as close together as possible. All connecting traces must be short, direct and thick. High current flowing and switching paths must be kept away from the feedback (VOUT, pin 3) terminal to avoid unwanted injection of noise into the feedback path.

Feedback Path

Feedback of the output voltage must be a separate trace separated from the power path. The output voltage sensing trace to the feedback (V_{OUT}, pin 3) pin should be connected to the output voltage directly at the anode of the output capacitor.

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External Component Reference Data

Device	V _{OUT}	Inductor Model	Inductor (L)	External MOSFET (M)	Diode (SD)	Output and Input Capacitor C _{OUT} /C _{IN}
NCP1550SN18T1	1.8 V	CDD5D23 6R8 (1A) CDRH6D38 6R8 (2A) Sumida	6.8 μΗ	NTGS3441T1 (1A) NTGS3443T1 (2A) ON Semiconductor	MBRM120LT3 ON Semiconductor	33 μF/33 μF (1A) 68 μF/33 μF (2A) KEMET (T494 series)
NCP1550SN19T1	1.9 V	CDC5D23 6R8 (1A) CDRH6D38 6R8 (2A) Sumida	6.8 μH	NTGS3441T1 (1A) NTGS3443T1 (2A) ON Semiconductor	MBRM120LT3 ON Semiconductor	33 μF/33 μF (1A) 68 μF/33 μF (2A) KEMET (T494 series)
NCP1550SN25T1	2.5 V	CDC5D23 5R6 (1A) CDRH6D38 5R0 (2A) Sumida	5.6 μΗ 5.0 μΗ	NTGS3441T1 (1A) NTGS3443T1 (2A) ON Semiconductor	MBRM120LT3 ON Semiconductor	33 μF/33 μF (1A) 68 μF/33 μF (2A) KEMET (T494 series)
NCP1550SN27T1	2.7 V	CDC5D23 5R6 (1A) CDRH6D38 5R0 (2A) Sumida	5.6 μΗ 5.0 μΗ	NTGS3441T1 (1A) NTGS3443T1 (2A) ON Semiconductor	MBRM120LT3 Semiconductor	33 μF/33 μF (1A) 68 μF/33 μF (2A) KEMET (T494 series)
NCP1550SN30T1	3.0 V	CDC5D23 4R7 (1A) CDRH6D28 5R0 (2A) Sumida	5.6 μΗ 5.0 μΗ	NTGS3441T1 (1A) NTGS3443T1 (2A) ON Semiconductor	MBRM120LT3 ON Semiconductor	33 μF/33 μF (1A) 68 μF/33 μF (2A) KEMET (T494 series)
NCP1550SN33T1	3.3 V	CD43 3R3 (1A) CDRH6D38 3R3 (2A) Sumida	3.3 μH	NTGS3441T1 (1A) NTGS3443T1 (2A) ON Semiconductor	MBRM120LT3 ON Semiconductor	68 μF/33 μF (1A) 100 μF/68 μF (2A) KEMET (T494 series)

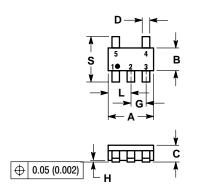
ORDERING INFORMATION

Part Number	Output Voltage (V _{OUT})	Switching Frequency	Device Marking	Package	Shipping [†]
NCP1550SN33T1	3.3 V		DCD	TSOP-5	
NCP1550SN33T1G	3.3 V		DCD	TSOP-5 (Pb-Free)	
NCP1550SN30T1	3.0 V		DBF	TSOP-5	
NCP1550SN27T1	2.7 V	000 -	DCB	TSOP-5	
NCP1550SN25T1	2.5 V	600 kHz	DCA	TSOP-5	3000 Tape & Reel
NCP1550SN19T1	1.9 V		DBE	TSOP-5	
NCP1550SN18T1	1.8 V	1	DBZ	TSOP-5	
NCP1550SN18T1G	1.8 V		DBZ	TSOP-5 (Pb-Free)	

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

PACKAGE DIMENSIONS

THIN SOT23-5/TSOP-5/SC59-5 **SN SUFFIX** CASE 483-02 ISSUE C



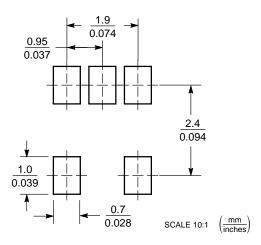




- NOTES:
 DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 CONTROLLING DIMENSION: MILLIMETER.
 MAXIMUM LEAD THICKNESS INCLUDES LEAD FINISH THICKNESS. MINIMUM LEAD THICKNESS IS THE MINIMUM THICKNESS OF BASE MATERIAL.
 A AND B DIMENSIONS DO NOT INCLUDE MOLD FLASH, PROTRUSIONS, OR GATE BURRS.

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	2.90	3.10	0.1142	0.1220
В	1.30	1.70	0.0512	0.0669
С	0.90	1.10	0.0354	0.0433
D	0.25	0.50	0.0098	0.0197
G	0.85	1.05	0.0335	0.0413
Н	0.013	0.100	0.0005	0.0040
J	0.10	0.26	0.0040	0.0102
κ	0.20	0.60	0.0079	0.0236
L	1.25	1.55	0.0493	0.0610
М	0	10	0	10
S	2.50	3.00	0.0985	0.1181

SOLDERING FOOTPRINT*



*For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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